Advanced MRI and fMRI Acquisition Methods

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National Institutes of Health



Outline

- NMR: Review of physics basics
- MR Imaging: tools and techniques
- K-space trajectories
- Image acceleration
- Controlling the image contrast

NMR: Nuclear Magnetic Resonance

- Effect is due to intrinsic spin of positively charged atomic nuclei of atoms.
- In the presence of an external magnetic field the nuclei absorb and re-emit electromagnetic radiation
- The radiation at a specific resonance frequency

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$$\omega = \gamma B$$

- ω : angular frequency. $\omega = 2\pi v$
- γ : gyromagnetic ratio
- B: strength of the external magnetic field

NMR: Nuclear Magnetic Resonance

- $\omega = \gamma B$
- For ¹H (aka protons): $\gamma = 42.58$ MHz / T where $\gamma = \gamma / 2\pi$
- Magnetization is a vector:

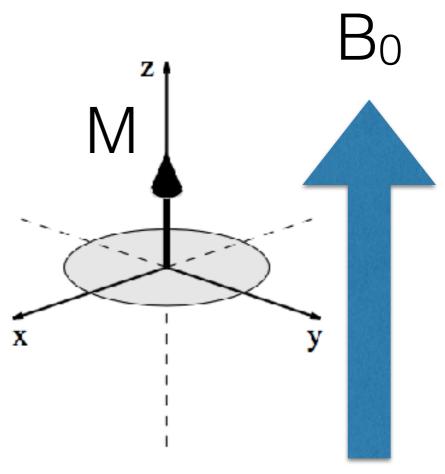
$$\mathbf{M} = (M_X, M_y, M_z)^T$$

At equilibrium:

$$\mathbf{M} = (0, 0, M_0)^T$$

where

$$\frac{M_0 = N\gamma \hbar^2 I_z (I_z + 1)B_0}{3kT}$$



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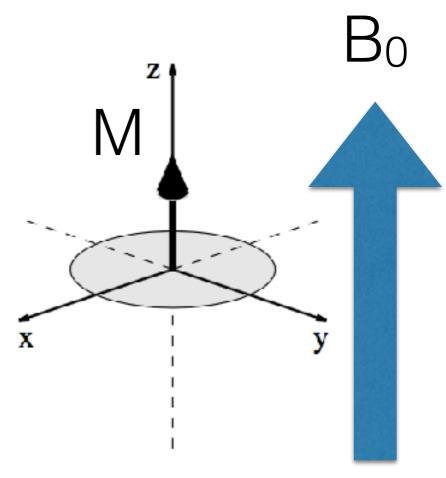
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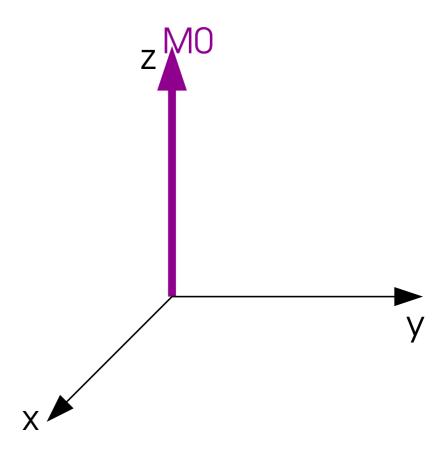
$$\frac{M_0 = N\gamma \hbar^2 I_z (I_z + 1)B_0}{3kT}$$





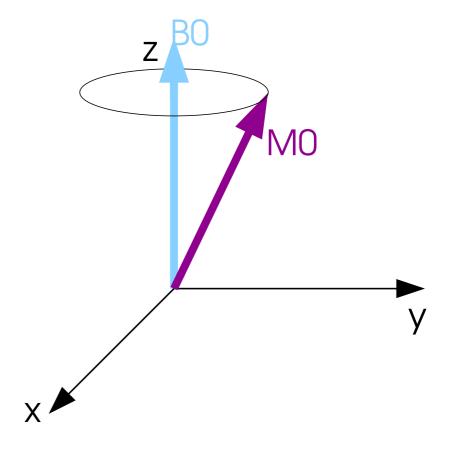
Excitation, Precession and the Rotating Frame

In lab frame at equilibrium



- Excitation is the process of tipping the magnetization away from the direction of the main magnetic field.
- Once excited, the magnetization precesses around the magnetic field with angular frequency

$$\omega = \gamma B$$

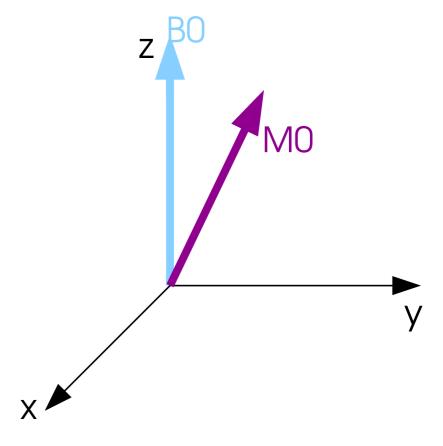


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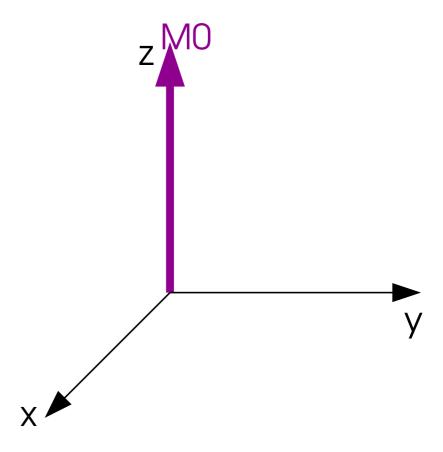
$$\omega = \gamma B$$

• It is convenient to work in a frame of reference rotating at $\omega = \gamma B$

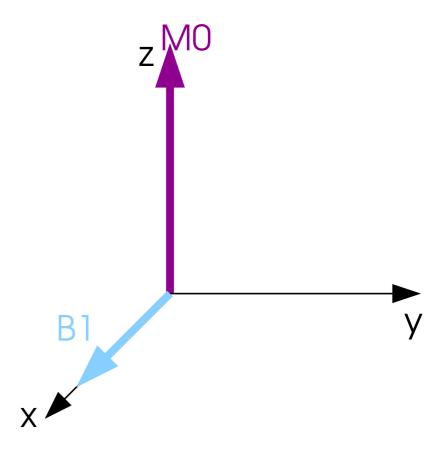


Excitation, Precession and the Rotating Frame

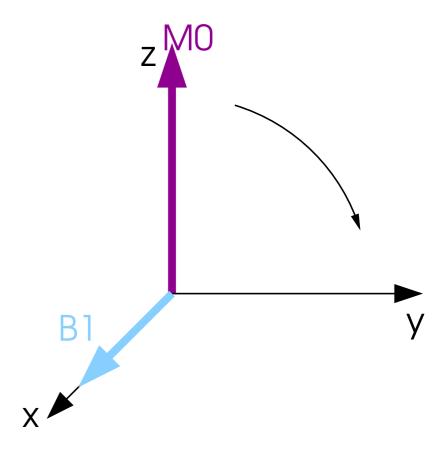
In rotating frame at equilibrium



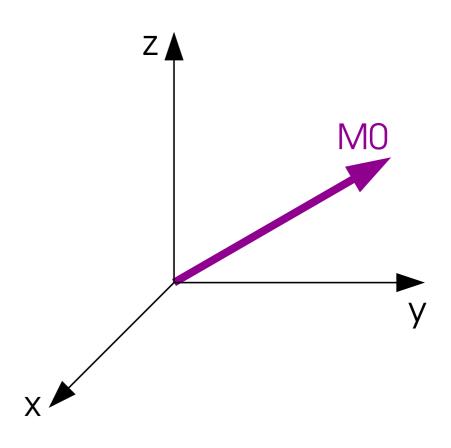
- In rotating frame at equilibrium
- Apply B₁ magnetic field along (rotating frame) x-axis



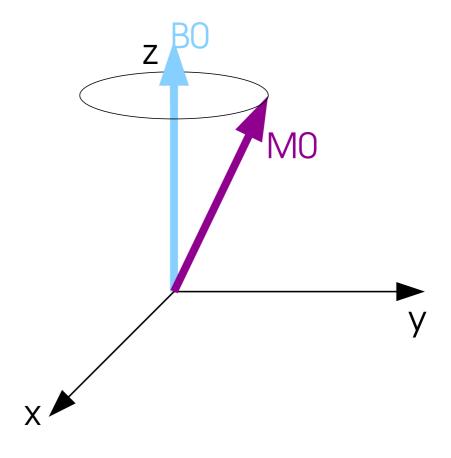
- In rotating frame at equilibrium
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- $\omega_1 = \gamma B_1$
- Magnetization rotates towards (rotating-frame) y-axis



- In rotating frame at equilibrium
- Apply B₁ magnetic field along (rotating-frame) x-axis
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- Turn off B1 field when magnetization reaches the appropriate flip angle with respect to the z-axis

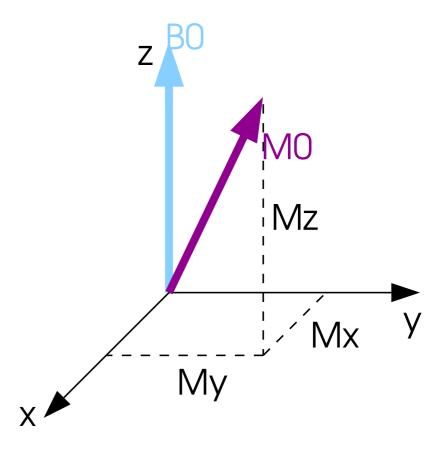


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- $\omega_1 = \gamma B_1$
- Magnetization rotates towards (rotating-frame) y-axis
- Turn off B1 field when magnetization reaches the appropriate flip angle with respect to the z-axis
- Magnetization precesses and relaxes back to equilibrium



MR signal

- $\mathbf{M} = (M_x, M_y, M_z)^T$
- M_z is the longitudinal component
- M_x,M_y are transverse components



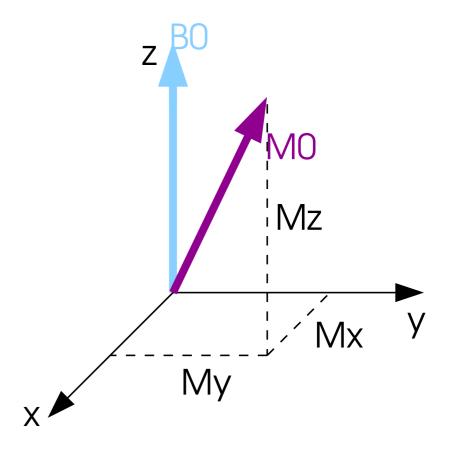
MR signal

- $\mathbf{M} = (M_X, M_y, M_z)^T$
- Mz is the longitudinal component
- M_x,M_y are transverse components

NMR signal is proportional to M_{xy} where:

$$M_{xy} = M_x + iM_y$$

 M_{xy} is considered to be a complex-valued signal induced in the receiver coil



MR relaxation

- Mz is the longitudinal component of M
- After excitation M_z relaxes back to M₀ by T₁ relaxation

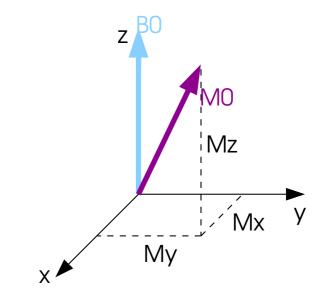
$$\frac{dM_Z}{dt} = \frac{(M_0 - M_Z)}{T_1}$$

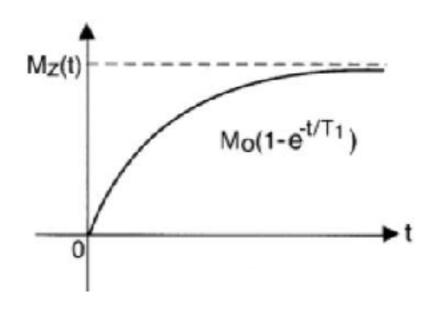
So that:

$$M_z(t) = M_0 + (M_z(0) - M_0)e^{-t/T1}$$

or, equivalently

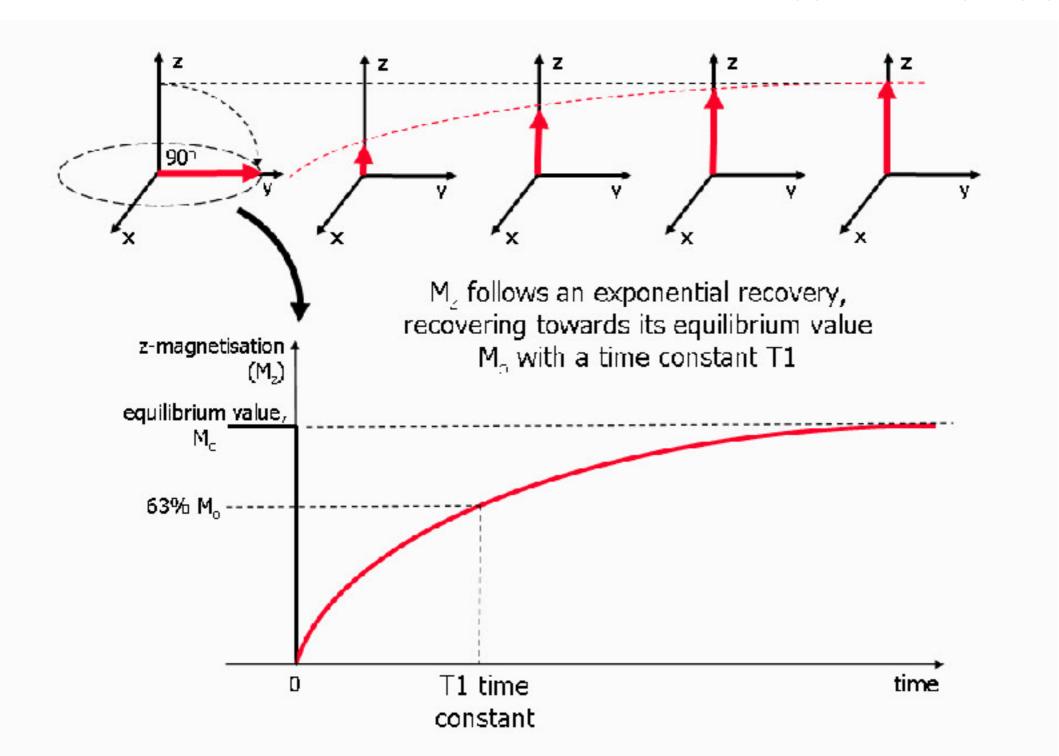
$$M_z(t) = M_z(0)e^{-t/T1} + M_0(1 - e^{-t/T1})$$





MR relaxation

$$M_z(t) = M_0 + (M_z(0) - M_0)e^{-t/T1}$$



from J. Ridgeway, JCMR, **12**:71, 2010

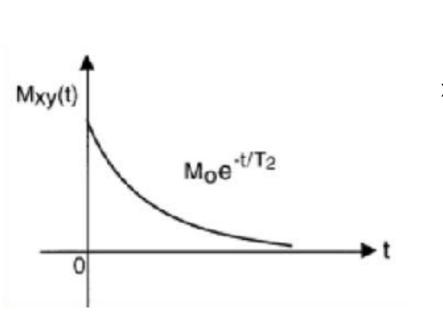
MR relaxation

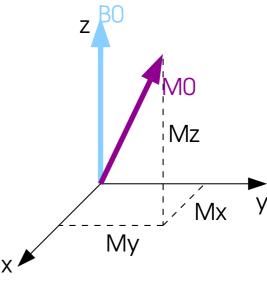
- M_{xy} is the transverse component of M
- After excitation M_{xy} relaxes back to zero by T₂ relaxation

$$\frac{dM_{xy}}{dt} = -\frac{M_{xy}}{T_2}$$

So that:

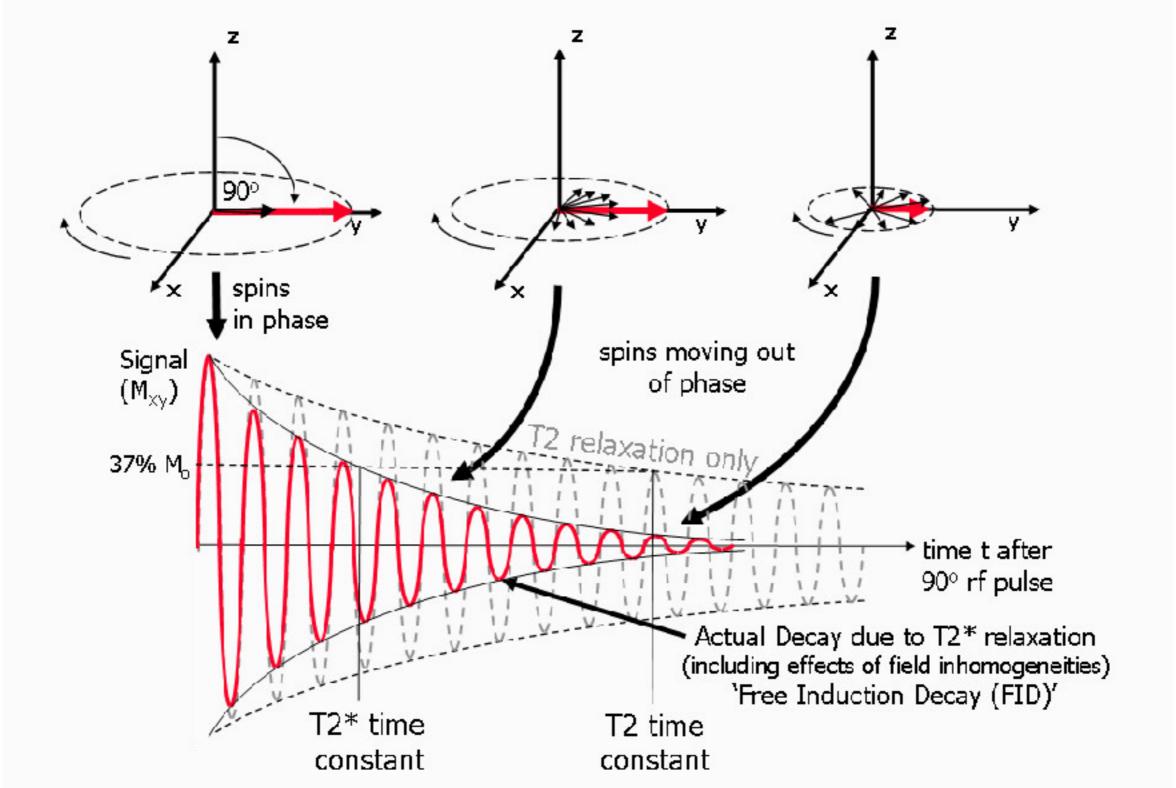
$$M_{xy}(t) = M_{xy}(0)e^{-t/T_2}$$





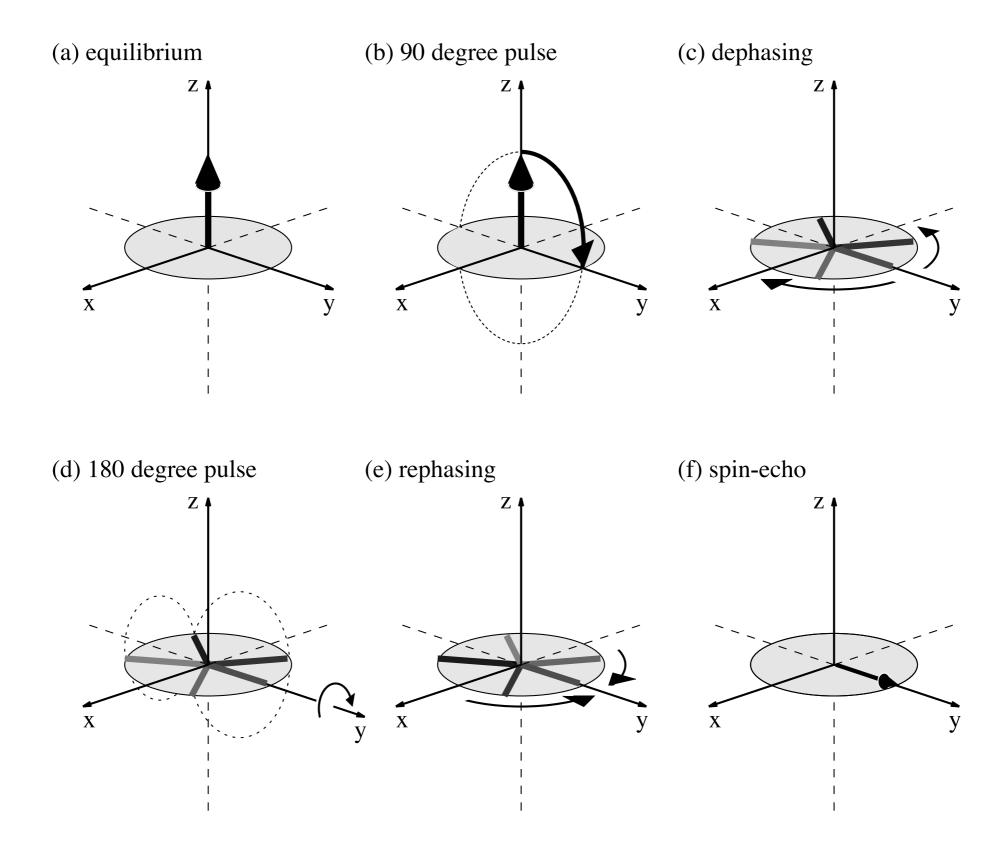
• Note that $T_2 <= T_1$ so that the MR signal generally dies faster than Mz regrows.

Intra voxel dephasing



from J. Ridgeway, JCMR, **12**:71, 2010

Spin-echo



Outline

- NMR: Review of physics basics
- MR Imaging: tools and techniques
 - Gradients
 - Selective excitation
 - Gradient echo
- K-space trajectories
- Controlling the image contrast
- Other stuff

- MR image formation is based on the equation: $\omega = \gamma B$
- In the main magnetic field, B_0 , we have: $\omega_0 = \gamma B_0$
- Superimpose a spatial magnetic field gradient,

$$\mathbf{G} = (\mathbf{G}_{x}, \mathbf{G}_{y}, \mathbf{G}_{z})^{\mathsf{T}}$$

then:

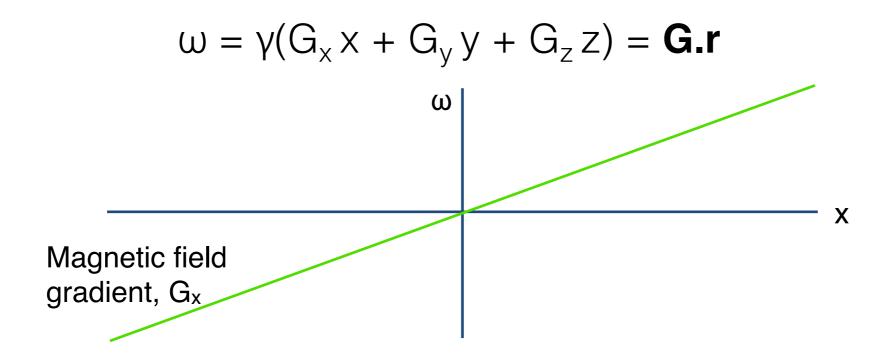
$$\omega = \gamma(G_x x + G_y y + G_z z) = \textbf{G.r}$$

$$\omega$$
 Magnetic field gradient, G_x

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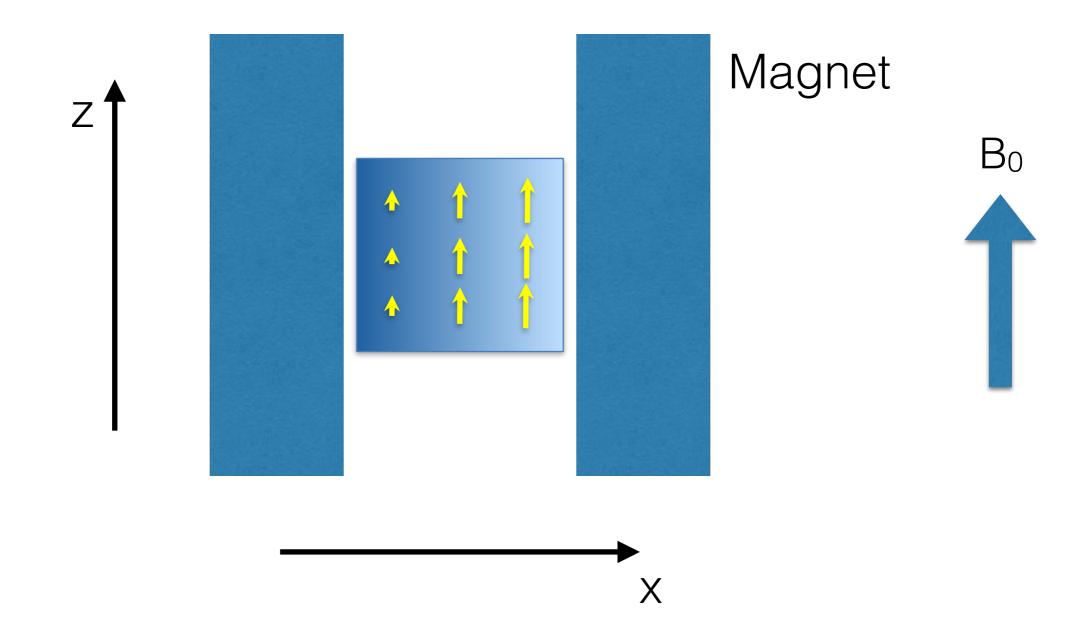
$$\mathbf{G} = (\mathbf{G}_{\mathsf{x}}, \mathbf{G}_{\mathsf{y}}, \mathbf{G}_{\mathsf{z}})^{\mathsf{T}}$$

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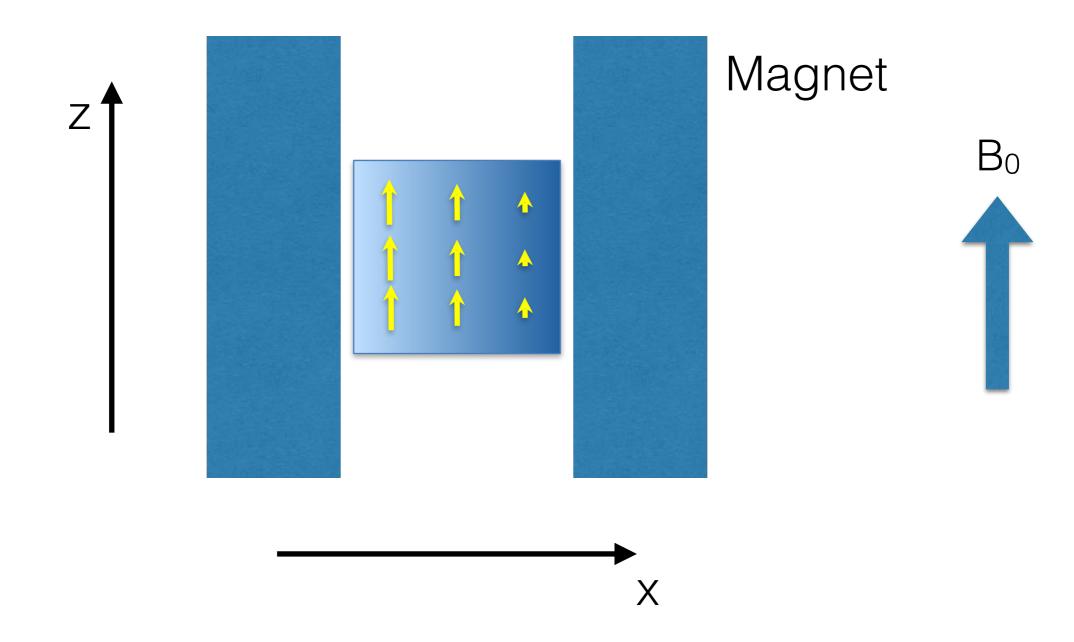


- Typical gradient fields are G = 30mT/m.
 i.e. +/-3mT at 10cm from isocenter.
- 1000 times smaller than B₀

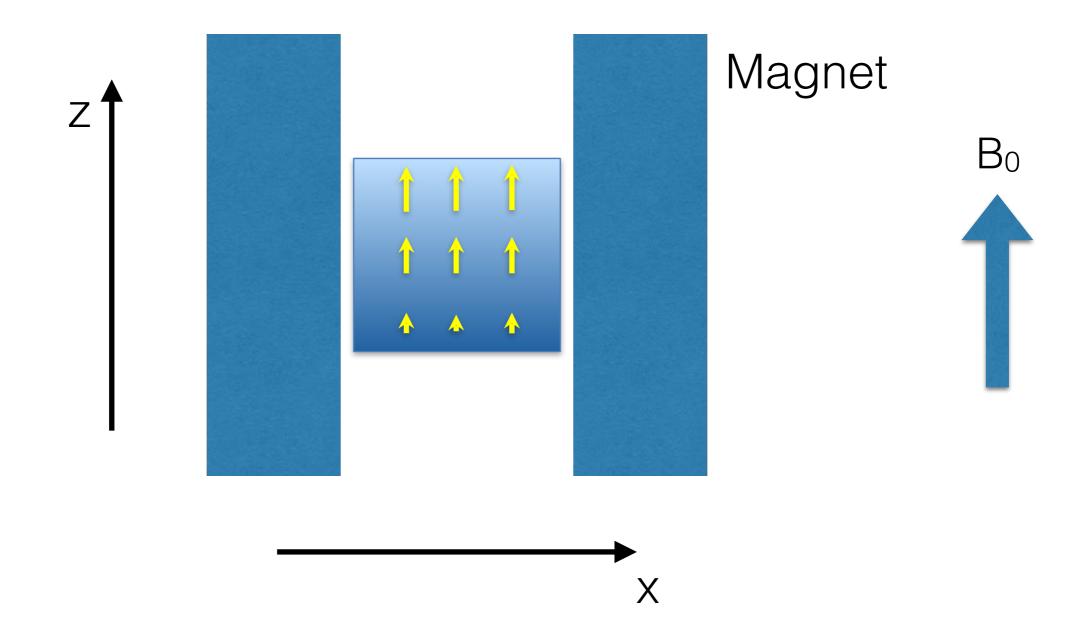
Gradient in +X



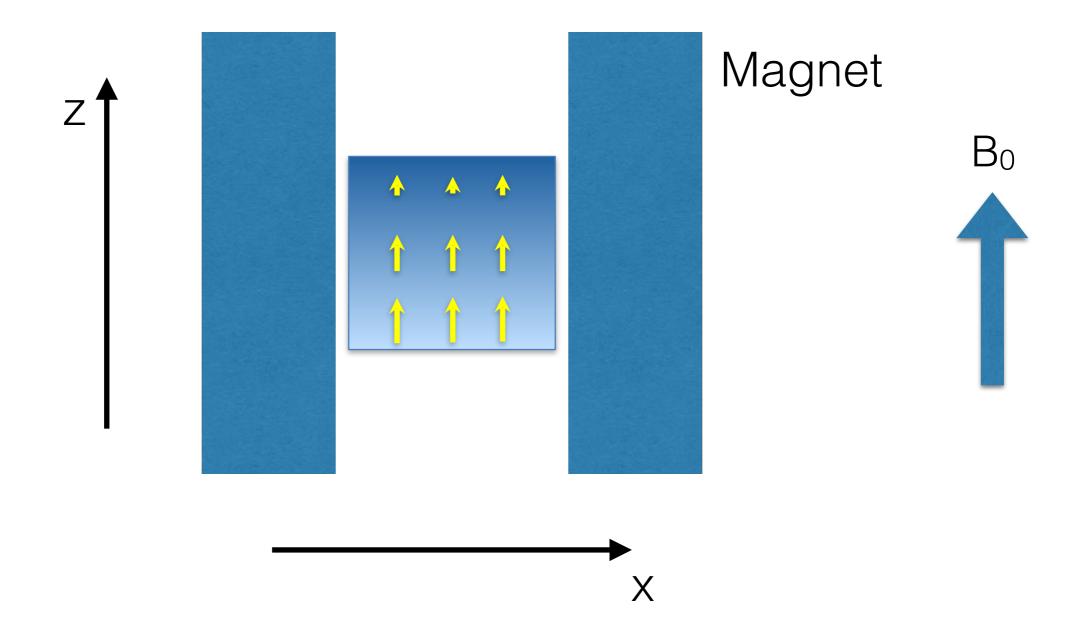
Gradient in -X



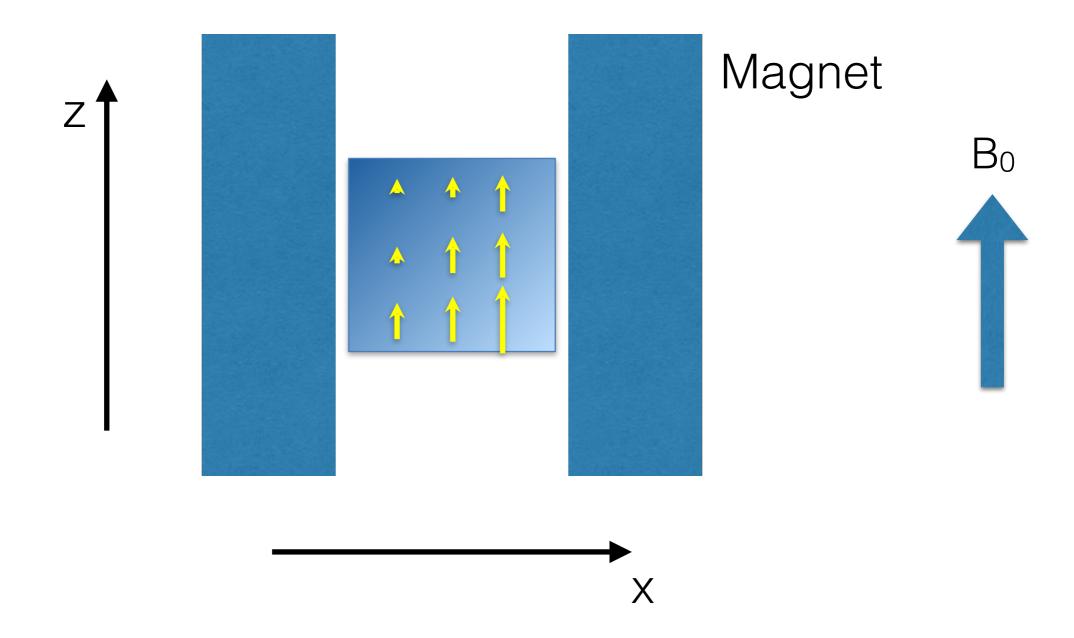
Gradient in +Z



Gradient in -Z



Gradients in both X and -Z

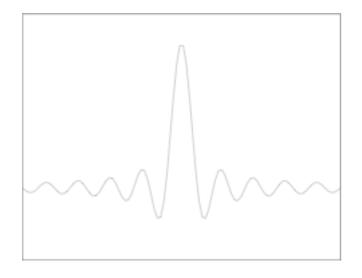


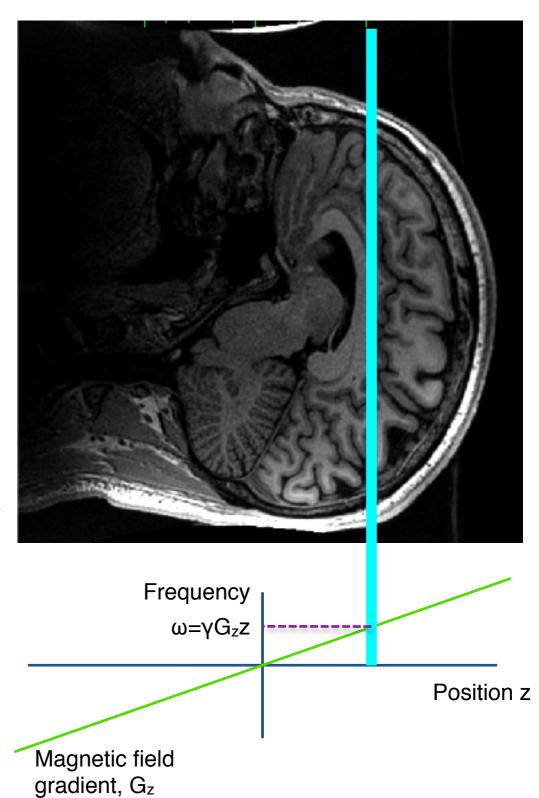
Slice selection

- Consider the slice of tissue at position z
- In the presence of gradient G_z, the local slice frequency is given by:

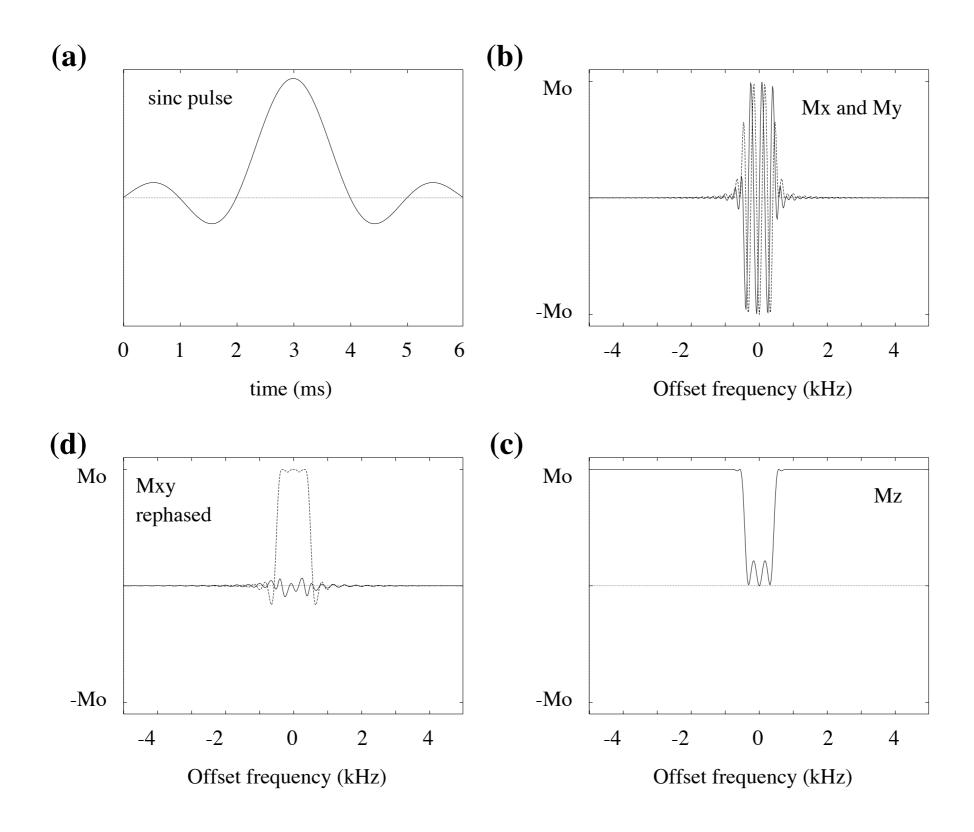
$$\delta \omega = \gamma G_z z$$

- Excite with frequency $\omega_0 + \delta \omega$ to move slice from isocenter to position of interest.
- Excite with an RF pulse that is the composition of a band of frequencies to define a particular slice width.
- Sinc pulse:

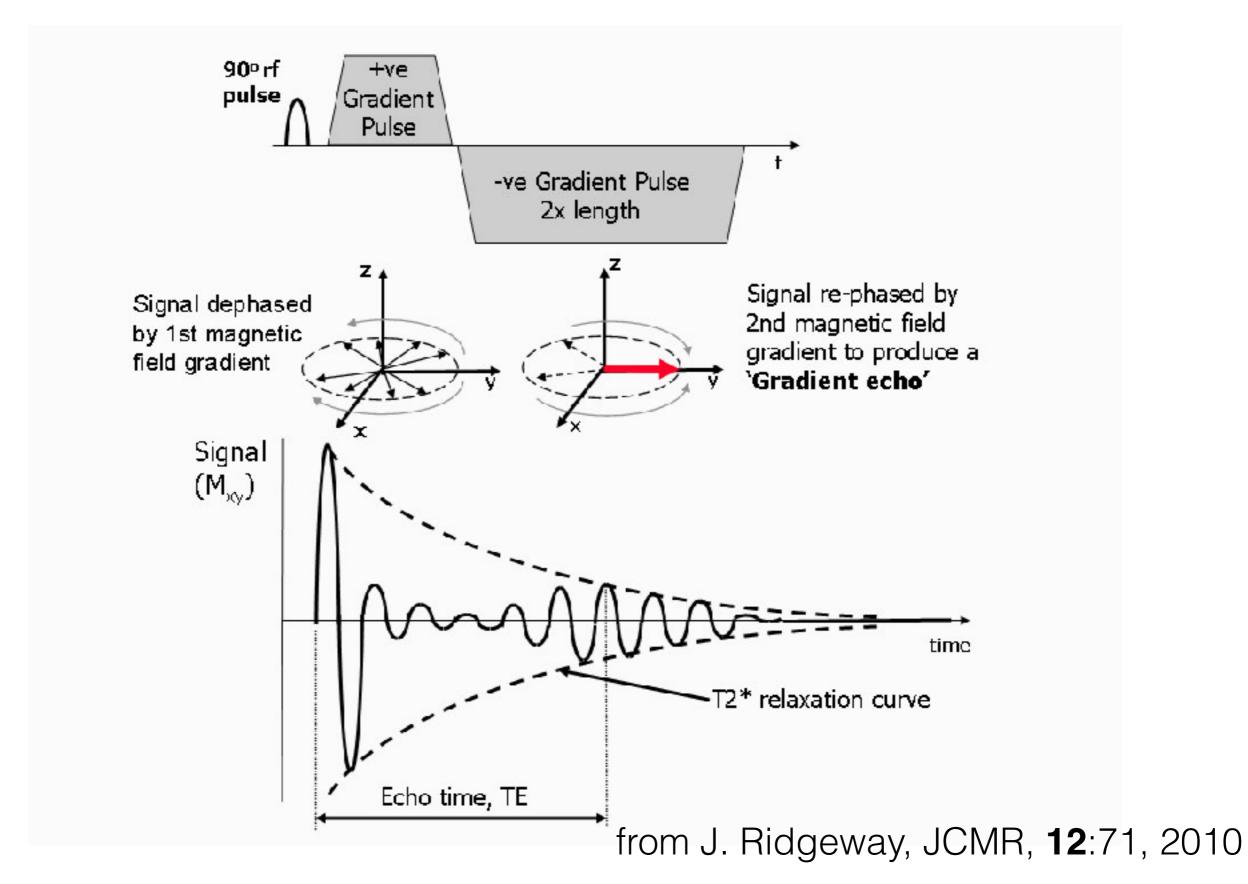




Selective excitation



Gradient echo



Outline

- NMR: Review of physics basics
- MR Imaging: tools and techniques
- K-space trajectories
 - Theory: MR signal and reconstruction equations
 - Fourier Imaging: readout and phase encoding
 - Echo planar imaging
 - Spiral Imaging
- Image acceleration
- Controlling the image contrast

Effect of imaging gradient

- MR image formation is based on the equation: $\omega = \gamma B$
- In the main magnetic field, B_0 , we have: $\omega_0 = \gamma B_0$
- Superimpose a spatial magnetic field gradient,

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then:

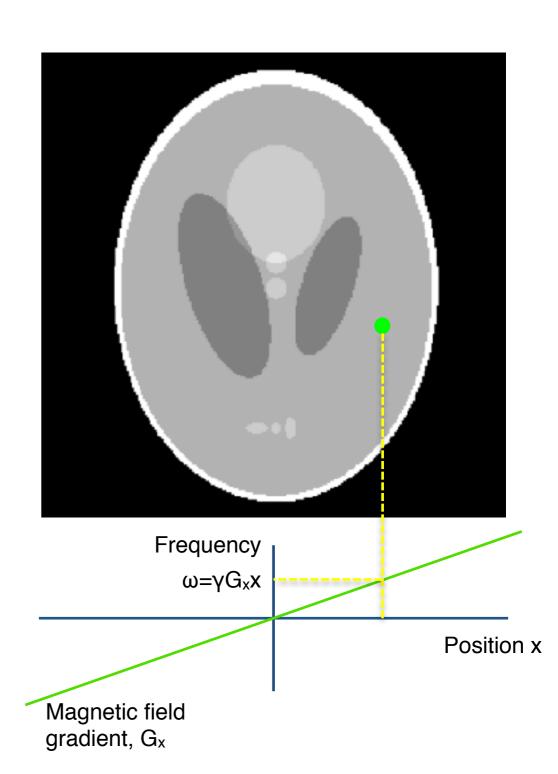
$$\omega = \gamma(G_x x + G_z y + G_z z) = \textbf{G.r}$$

$$\omega$$
 Magnetic field gradient, G_x

MR Imaging Theory

- Consider the green blob of tissue...
- The frequency is given by:

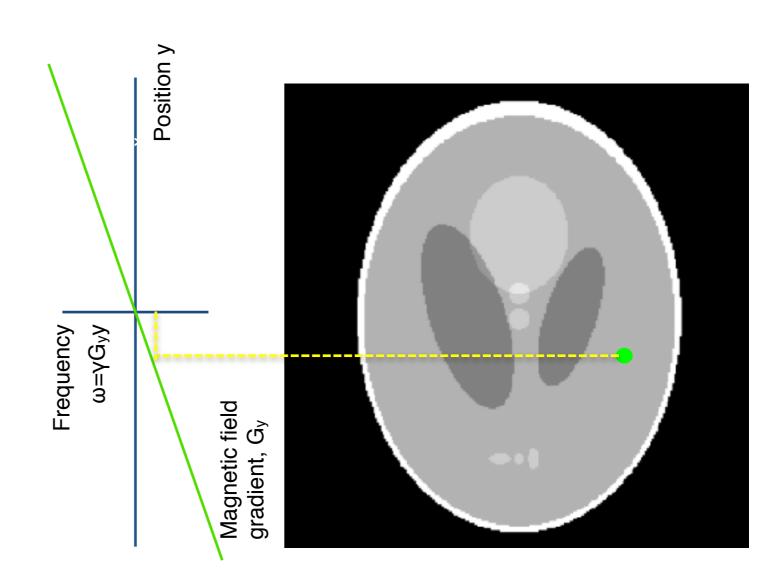
$$\delta\omega = \gamma \mathbf{G}(t) \cdot \mathbf{r}(t)$$



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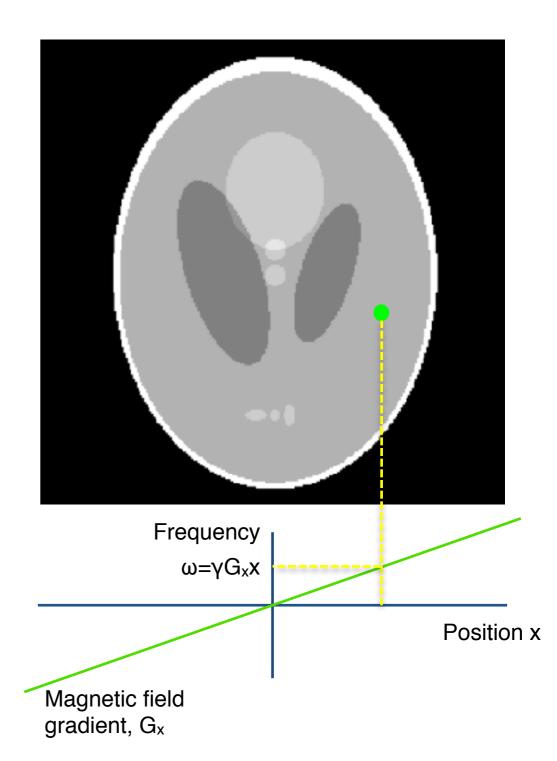


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Over time, phase accumulates as:

$$\delta\theta = \gamma \int_0^t \mathbf{G}(t')dt' \cdot \mathbf{r}(t)$$



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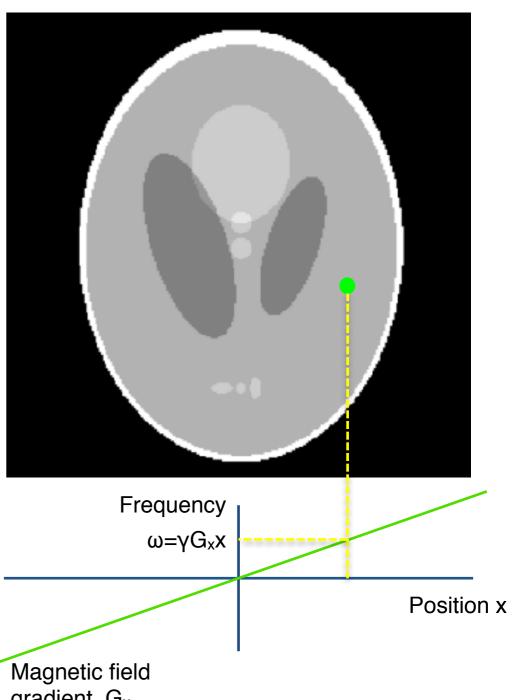
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Signal from the whole slice is given by:

$$S(G,t) = A \int_{V} \rho(\mathbf{r}) \exp \left[i\gamma \int_{0}^{t} \mathbf{G}(t') dt' \cdot \mathbf{r} \right] d^{3}\mathbf{r}$$



gradient, G_x

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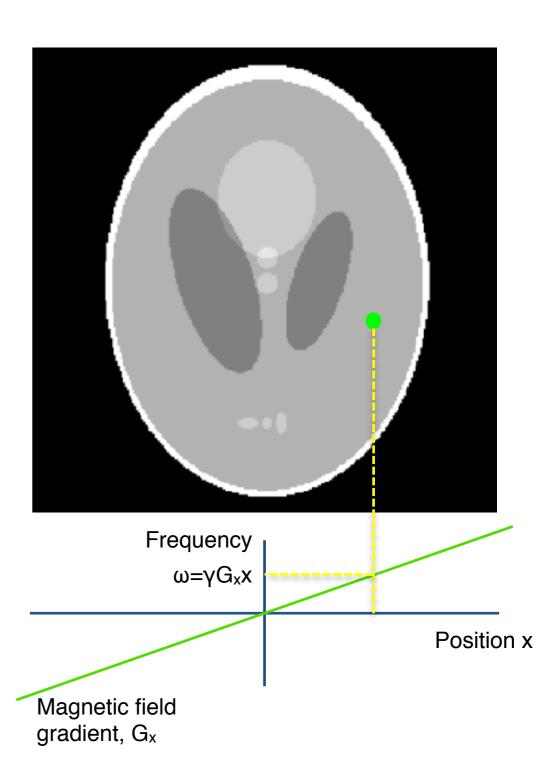
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Write:

$$\mathbf{k}(t) = \frac{\gamma}{2\pi} \int_0^t \mathbf{G}(t')dt'$$



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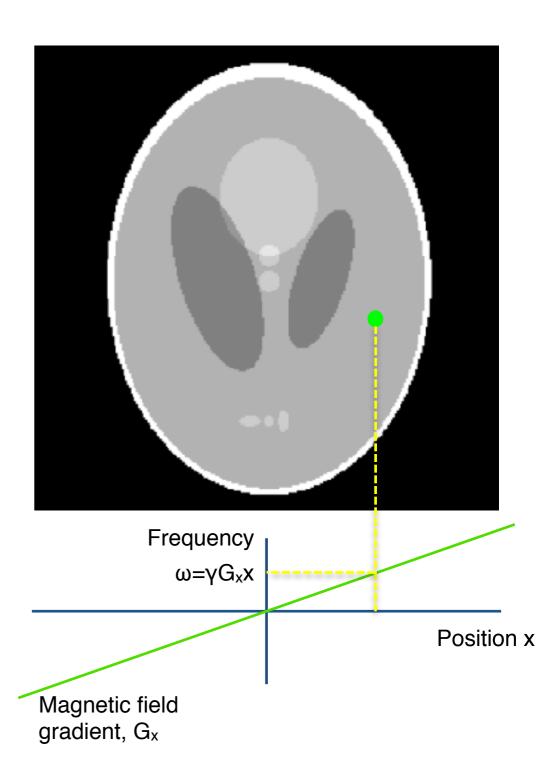
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$$S(\mathbf{k}) = \int_{V} \rho(\mathbf{r}) \exp(i2\pi \mathbf{k} \cdot \mathbf{r}) d^{3}\mathbf{r}$$



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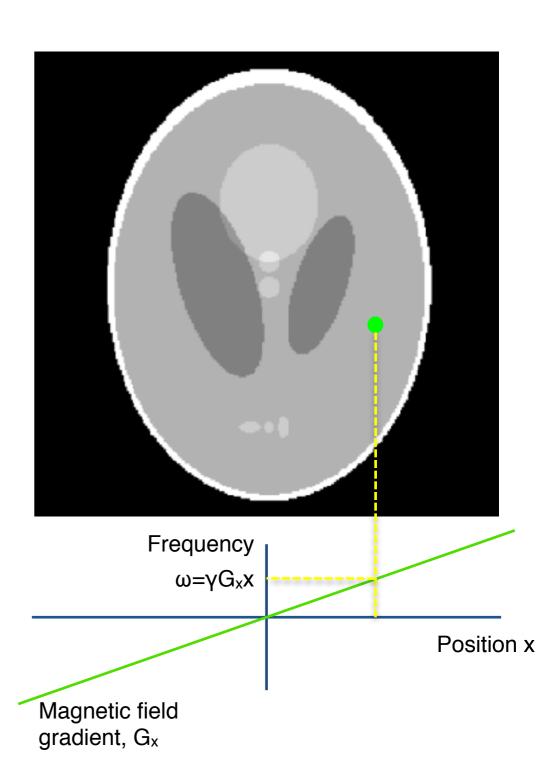
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$$\rho(\mathbf{r}) = \int_{\mathbb{R}^3} S(\mathbf{k}) \exp(-i2\pi \mathbf{k} \cdot \mathbf{r}) d^3 \mathbf{k}$$

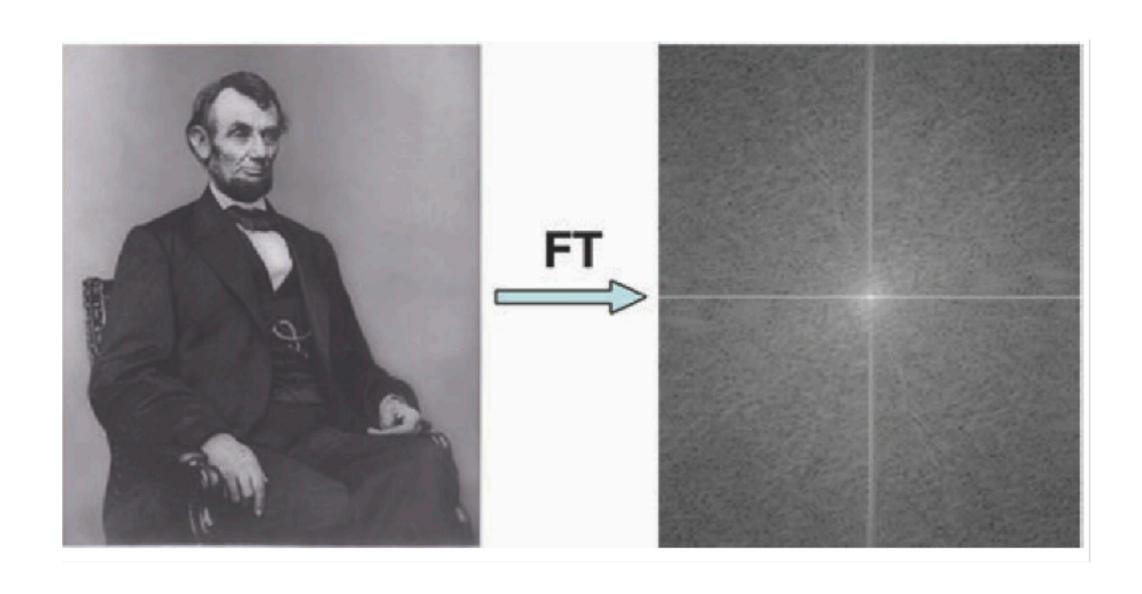


Fourier transform to k-space

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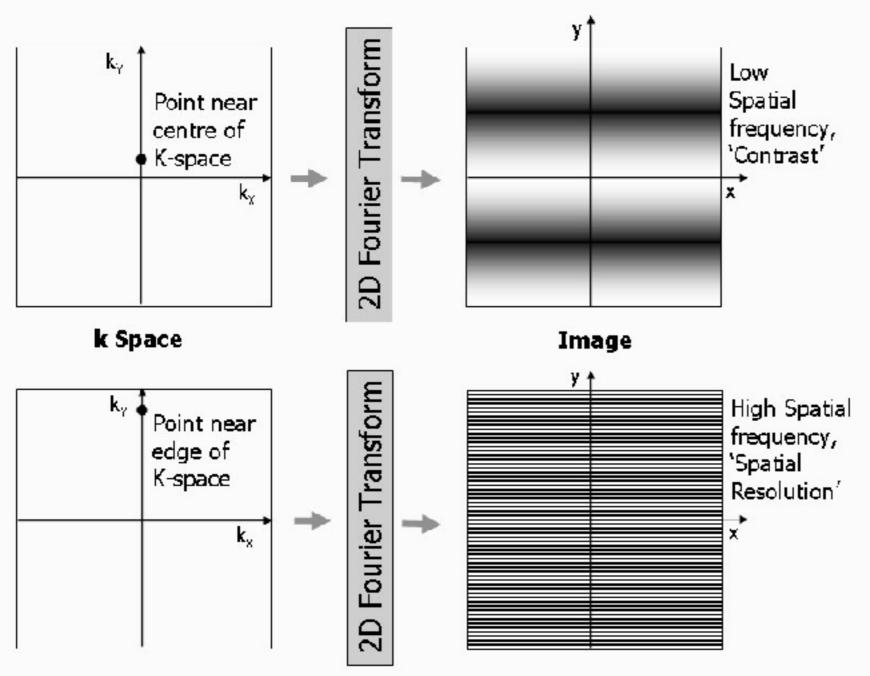


K-space

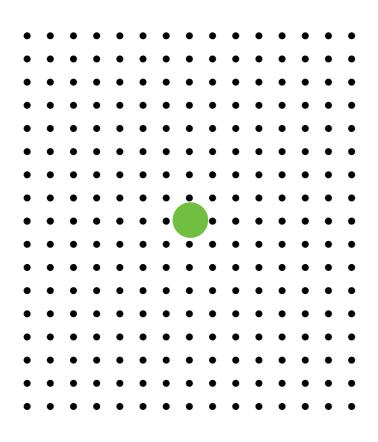
Spatial frequencies

$$\mathbf{k}(t) = \frac{\gamma}{2\pi} \int_0^t \mathbf{G}(t')dt'$$

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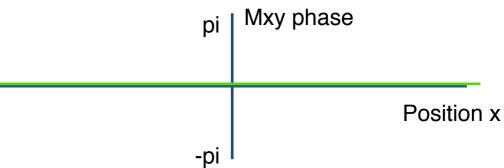


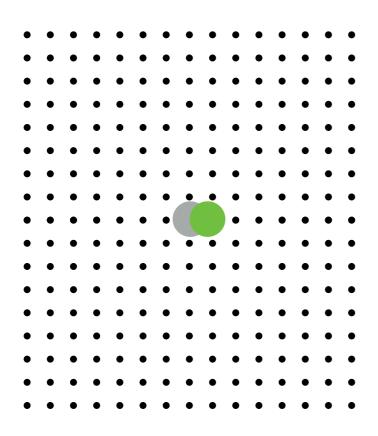
from J. Ridgeway, JCMR, **12**:71, 2010



 At center of k-space there is no Mxy phase across the image

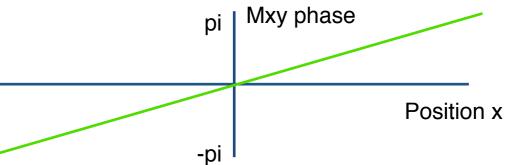


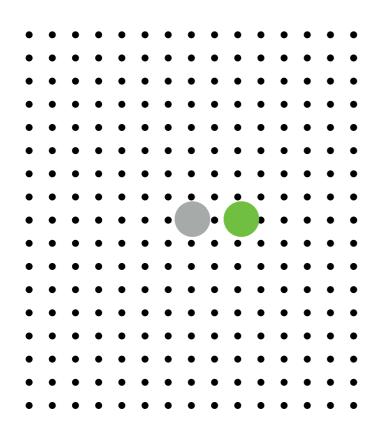




 Moving one k-space sample puts 2pi (-pi to pi) across the whole image FOV

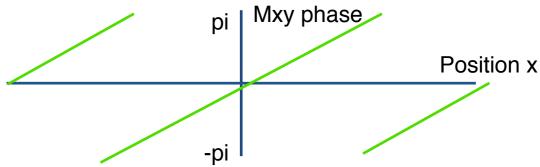


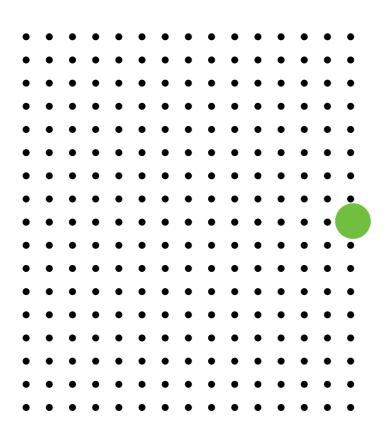




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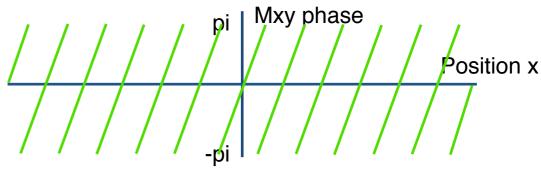






 At the edge of the k-space sampling region we have pi phase across each pixel/ voxel.



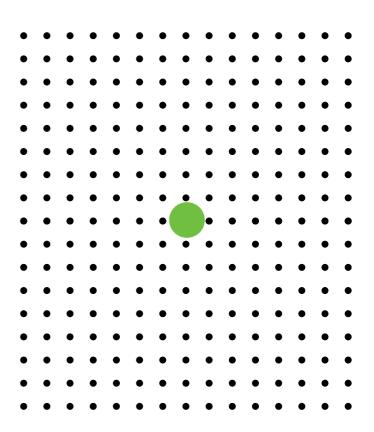


k-space trajectories

$$\mathbf{k}(t) = \frac{\gamma}{2\pi} \int_0^t \mathbf{G}(t')dt'$$

$$S(\mathbf{k}) = \int_{V} \rho(\mathbf{r}) \exp(i2\pi \mathbf{k} \cdot \mathbf{r}) d^{3}\mathbf{r}$$

- Sample all points in k-space to acquire sufficient data for image reconstruction.
- Initial position: origin
- k(t) is the sampling position
- G(t) is the velocity through k-space
- Sample spacing: $\delta \mathbf{k} = 1/FOV$
- Sampling extent: $\Delta \mathbf{k} = 1/\text{pixelsize}$

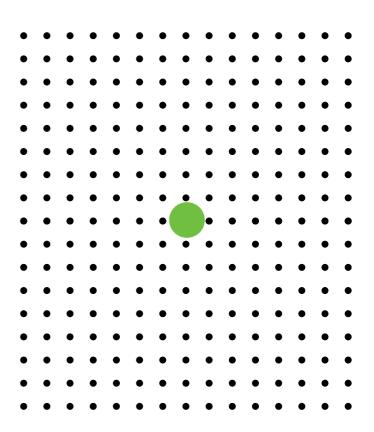


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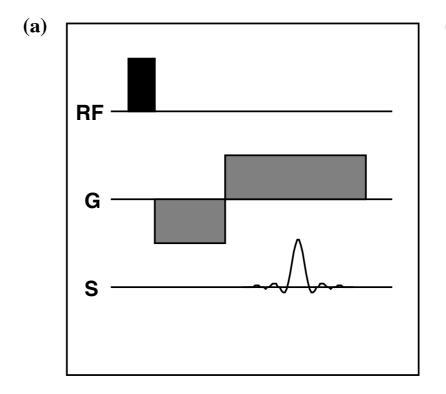


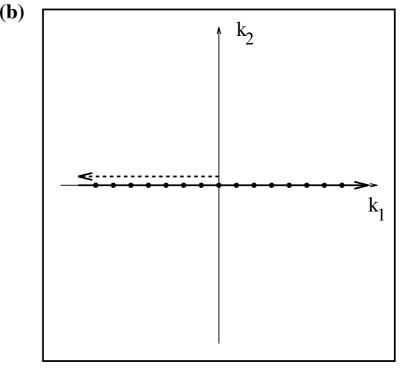
Gradient echo

 Forms echo signal with spatial encoding in the gradient direction

$$\mathbf{k}(t) = \frac{\gamma}{2\pi} \int_0^t \mathbf{G}(t')dt'$$

$$S(\mathbf{k}) = \int_{V} \rho(\mathbf{r}) \exp(i2\pi \mathbf{k} \cdot \mathbf{r}) d^{3}\mathbf{r}$$



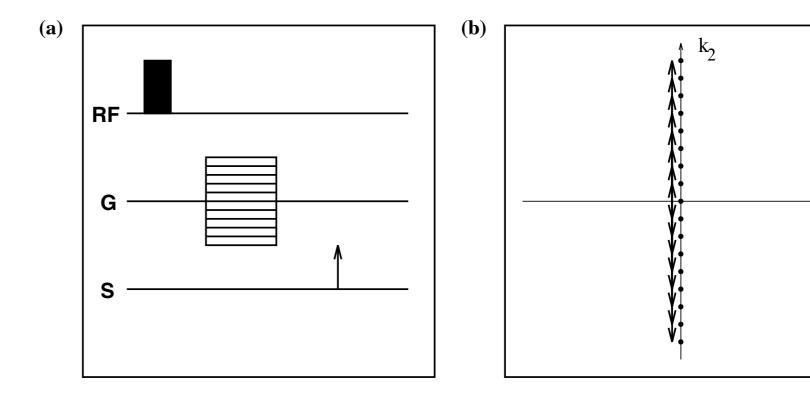


Phase encoding

 The phase encoding gradient offsets each acquisition in an orthogonal direction to the readout and slice

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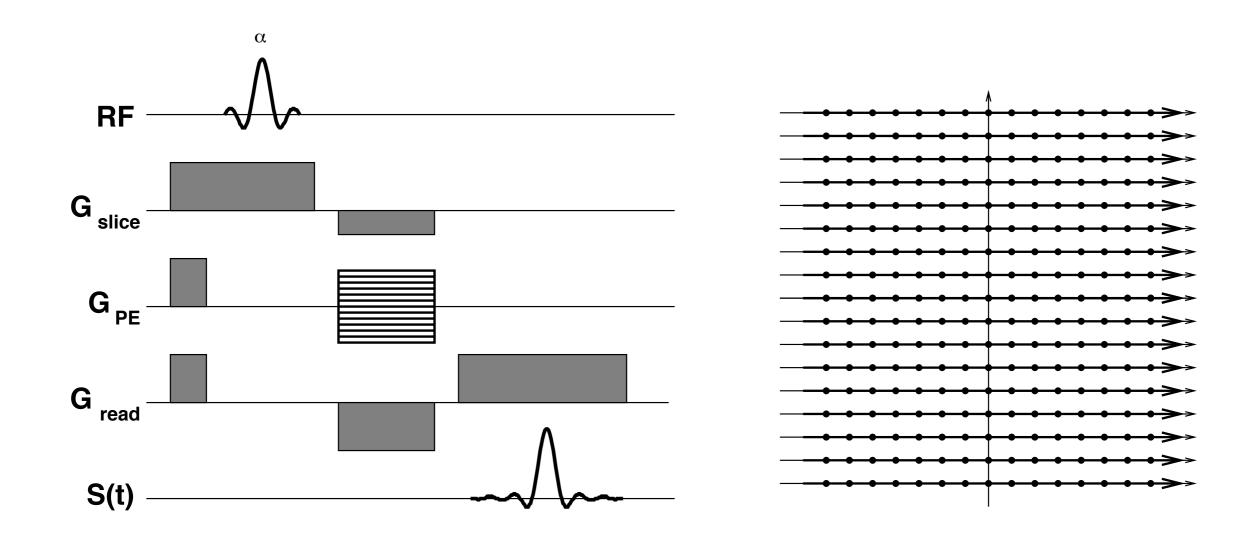


 $\mathbf{k}(t) = \frac{\gamma}{2\pi} \int_0^t \mathbf{G}(t')dt'$

2D Gradient echo imaging

$$S(\mathbf{k}) = \int_{V} \rho(\mathbf{r}) \exp(i2\pi \mathbf{k} \cdot \mathbf{r}) d^{3}\mathbf{r}$$

 Slice selective excitation combined with gradient echo in one direction and phase encoding in the other

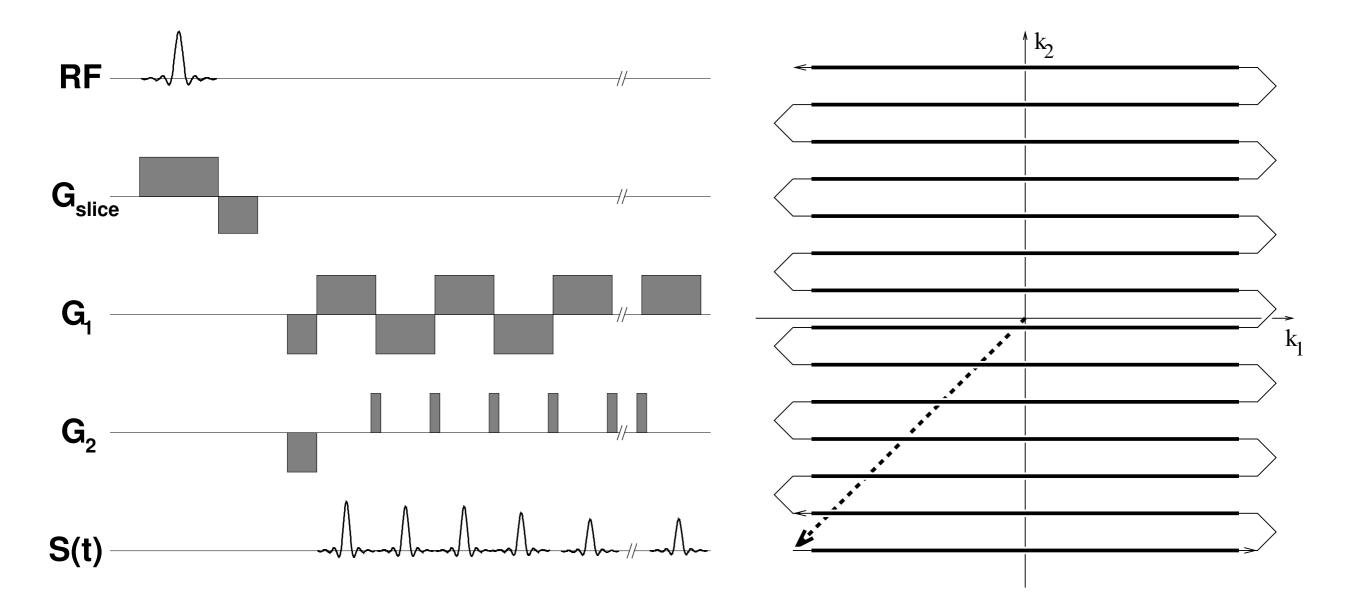


 $\mathbf{k}(t) = \frac{\gamma}{2\pi} \int_0^t \mathbf{G}(t')dt'$

Echo planar Imaging

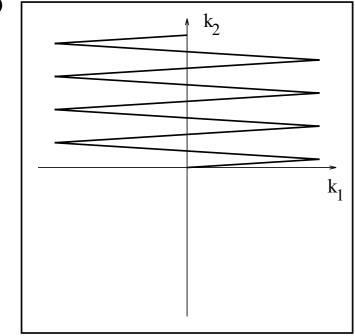
$$S(\mathbf{k}) = \int_{V} \rho(\mathbf{r}) \exp(i2\pi \mathbf{k} \cdot \mathbf{r}) d^{3}\mathbf{r}$$

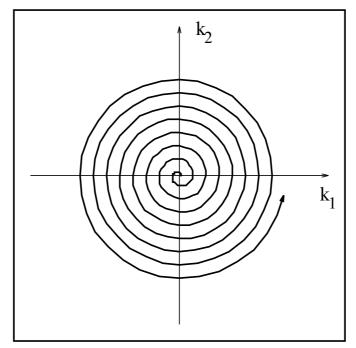
- Acquire the whole 2D k-space after excitation
- Time varying gradients during the acquisition

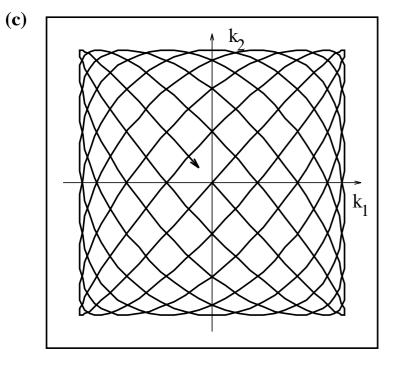


Spirals etc...

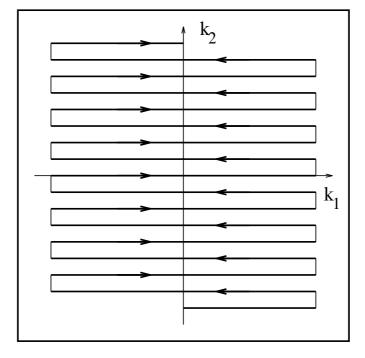








(d)



$$\mathbf{k}(t) = \frac{\gamma}{2\pi} \int_0^t \mathbf{G}(t')dt'$$

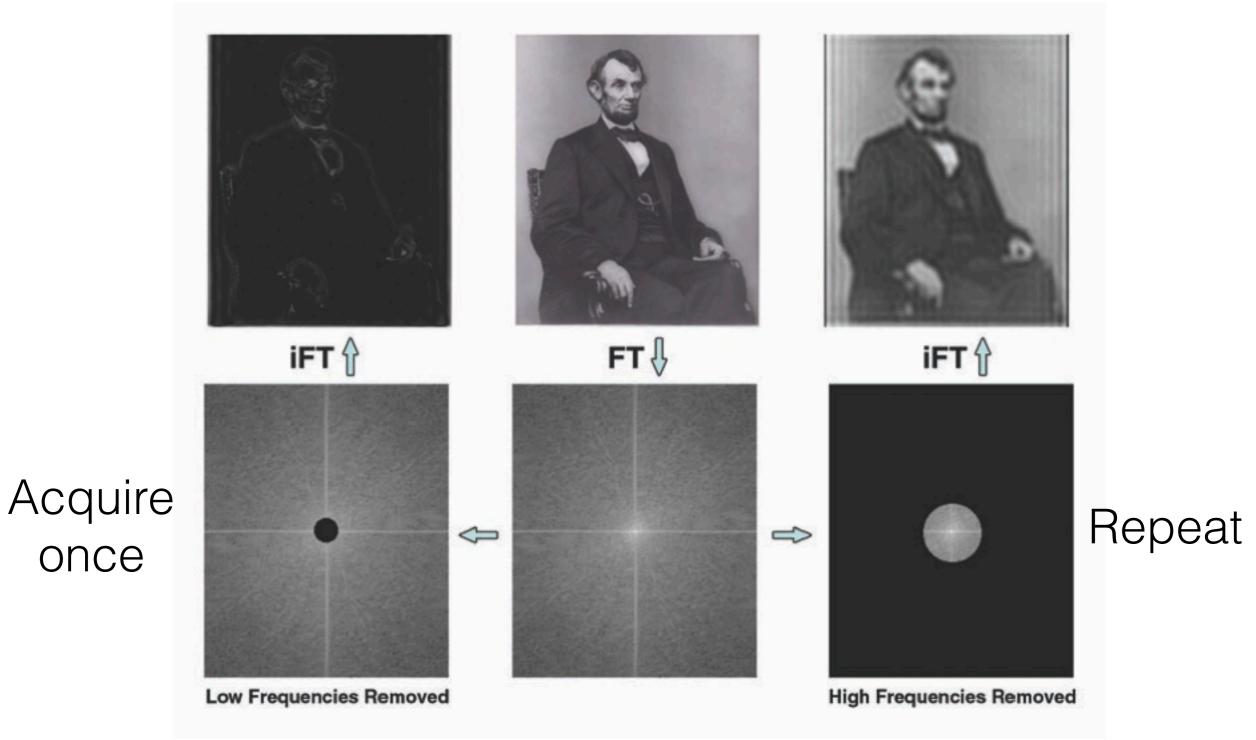
$$S(\mathbf{k}) = \int_{V} \rho(\mathbf{r}) \exp(i2\pi \mathbf{k} \cdot \mathbf{r}) d^{3}\mathbf{r}$$

Accelerated Acquisitions

Improving the temporal resolution

- Long image acquisition times
 - low temporal resolution
 - reduce coverage
 - increase sensitivity to subject motion
 - EPI: increase distortion
 - fMRI: reduce sensitivity to rapid events
- Partial k-space acquisition
 - partial echo
 - partial k-space
- Parallel imaging
 - SENSE
 - GRAPPA
- Multiband / Simultaneous multi-slice imaging

keyhole imaging



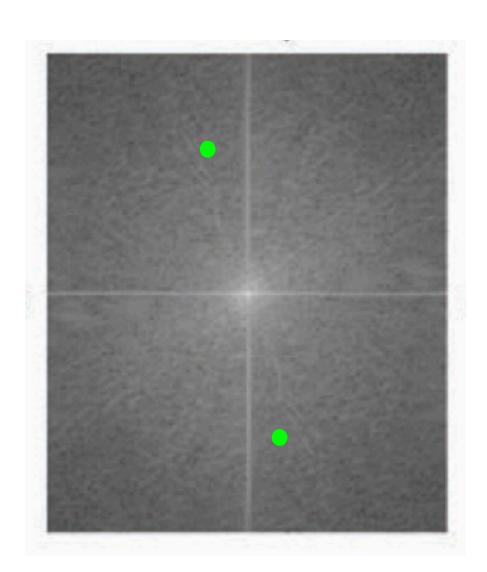
AJNR, Gallagher, DOI:10.2214/AJR.07.2874

Partial k-space

- Assume underlying image is real-valued
- Then k-space should be conjugate symmetric

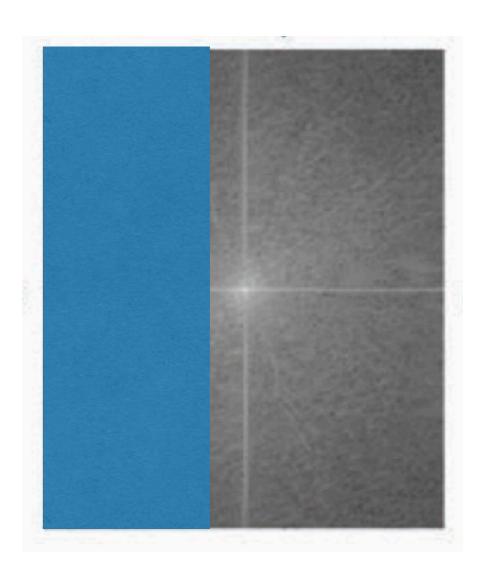
$$S(kx, ky) = S^*(-kx, -ky)$$

- Synthesize missing conjugate data during image reconstruction
- Need some additional lines near center of k-space to account for mild background phase roll across FOV (e.g. due to receiver coils)



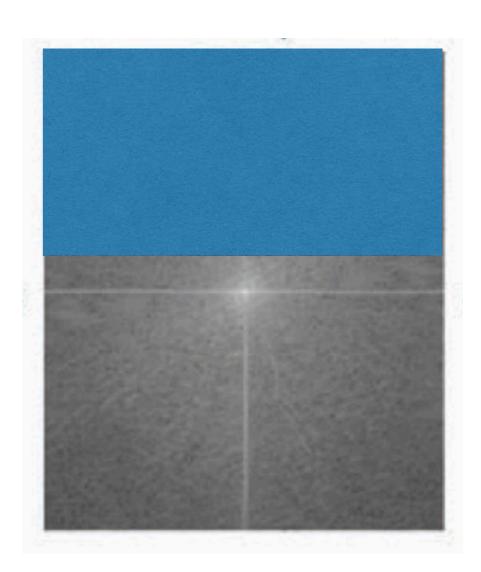
Partial k-space

- Partial echo / Asymmetric echo
 - Short TE



Partial k-space

- Partial NEX / Fractional k-space
 - Less TRs needed to form image



Multiple RF receiver coils

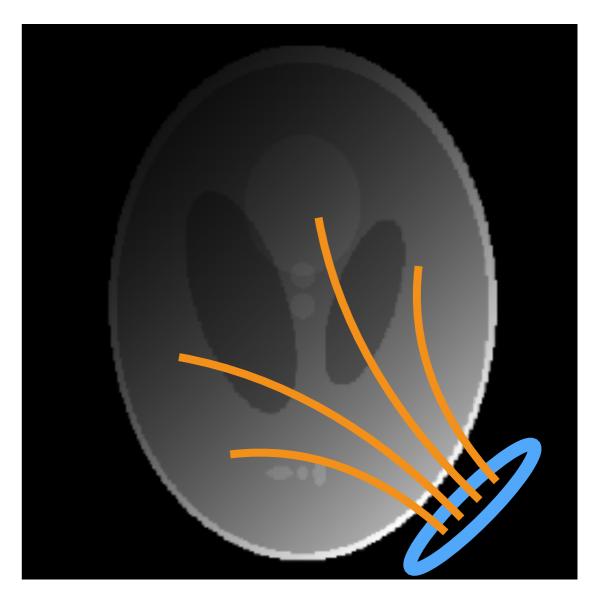
- Modern MRI systems acquire signals from multiple receiver coils
- Typically 8-64 channels



Multiple RF receiver coils

- Modern MRI systems acquire signals from multiple receiver coils
- Typically 8-64 channels
- Each coil has a distinct spatial sensitivity profile in space
- The MR signal from each receiver channel is weighted by the corresponding coil's sensitivity profile
- This provides an additional mechanism for positional encoding the MR signal

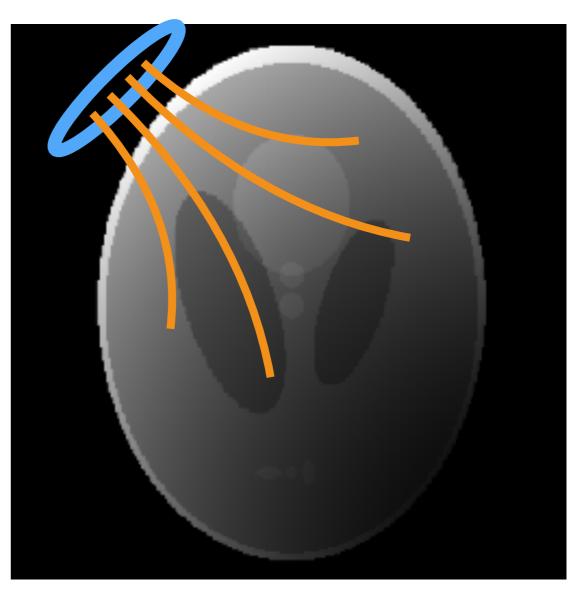
Image from coil 1



Multiple RF receiver coils

- Modern MRI systems acquire signals from multiple receiver coils
- Typically 8-64 channels
- Each coil has a distinct spatial sensitivity profile in space
- The MR signal from each receiver channel is weighted by the corresponding coil's sensitivity profile
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Image from coil 2



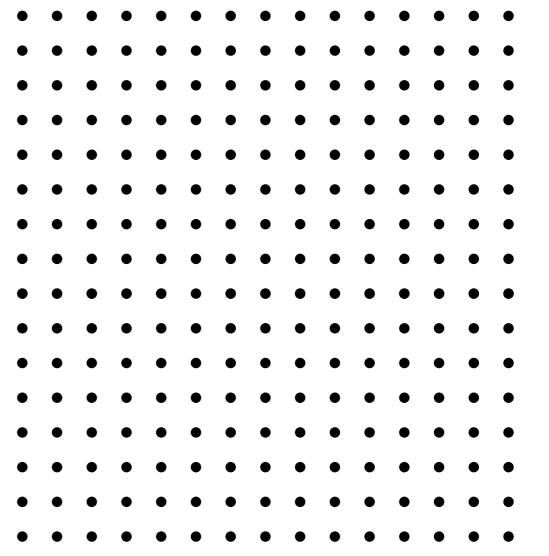
Undersampling k-space

- Regular acquisition
- Inter-sample spacing defines the FOV of the final image

1/FOV **\$**

Inverse relationship

```
dk = 1/FOV
```

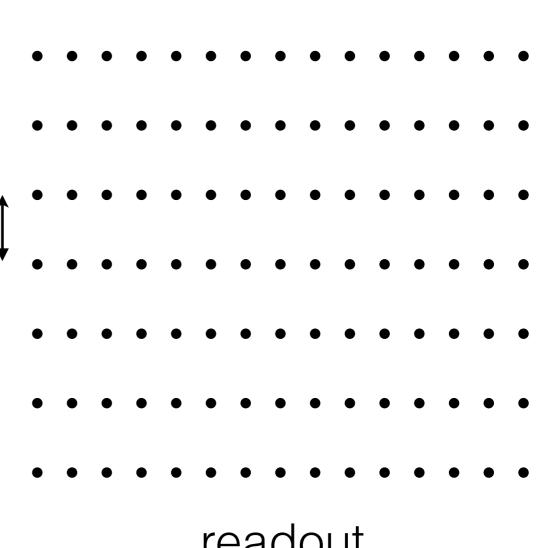


readout

Phase encode

Undersampling k-space

- Acquire only even-numbered kspace lines
- Effectively 1/2 FOV in phase encoding direction
- FOV in readout direction is unaffected



readout

SENSE example (R=2)

- Acquire only even-numbered kspace lines
 - effectively 1/2 FOV in phase encoding direction
 - aliased images
- Solve linear system to unwrap the aliasing at l(x, y) - green dot.

$$S_1(x,y) = W_{11} I(x,y) + W_{12} I(x, y+N/2)$$

$$S_2(x,y) = W_{21} I(x,y) + W_{22} I(x, y+N/2)$$

etc.

Matrix form: S = EI

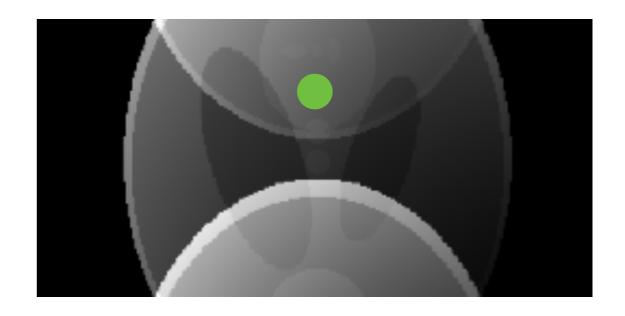
Solution: I = pinv(E).S

- E is the coil encoding matrix
- Serious noise amplification (g-factor) for large R

Image from coil 1

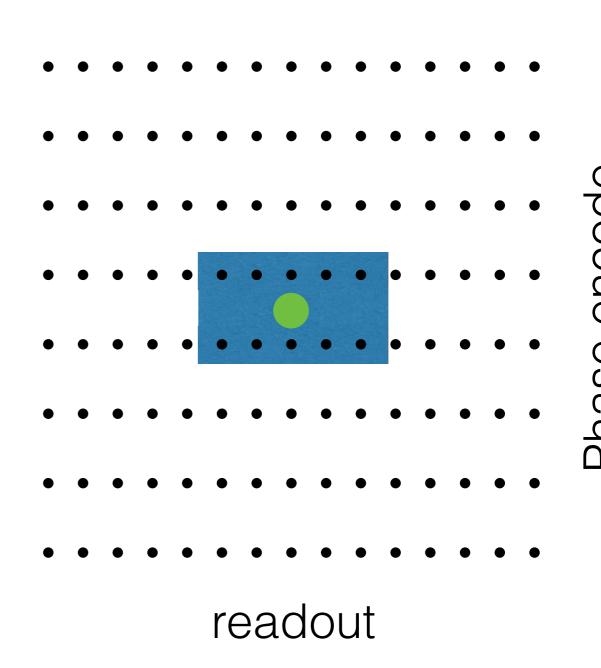


Image from coil 2



GRAPPA (R=2 example)

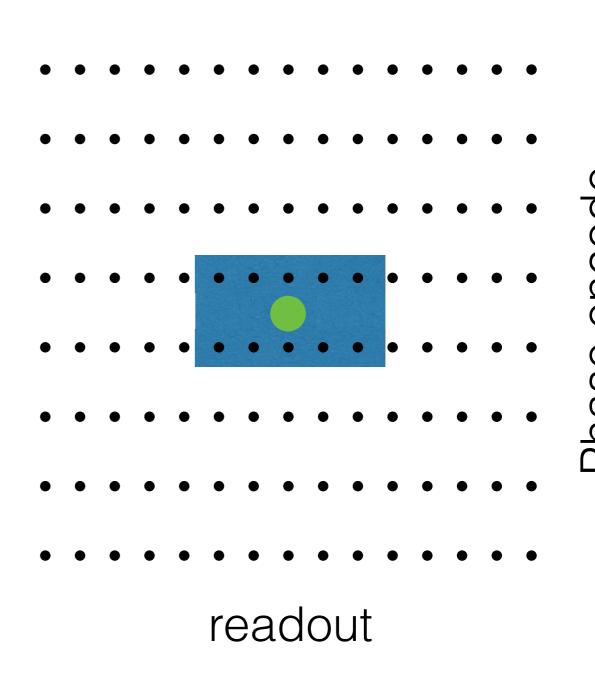
- Similar k-space undersampling as SENSE
- Data is interpolated in k-space from neighboring samples



GRAPPA (R=2 example)

- Similar k-space undersampling as SENSE
- Data is interpolated in k-space from neighboring samples

 Both SENSE and GRAPPA require additional calibration data to perform their reconstruction

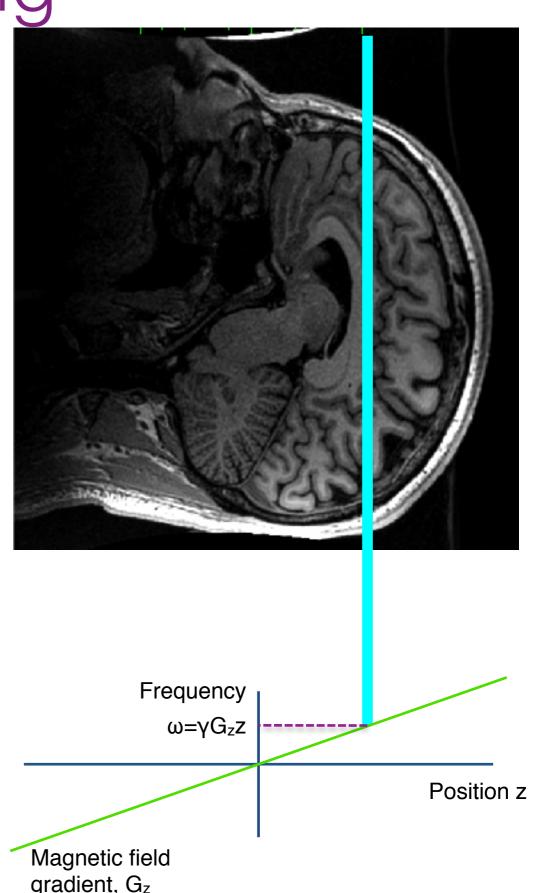


Simultaneous multi-slice imaging

- Consider the slice of tissue at position z
- In the presence of gradient G_z, the local slice frequency is given by:

$$\delta \omega = \gamma G_z z$$

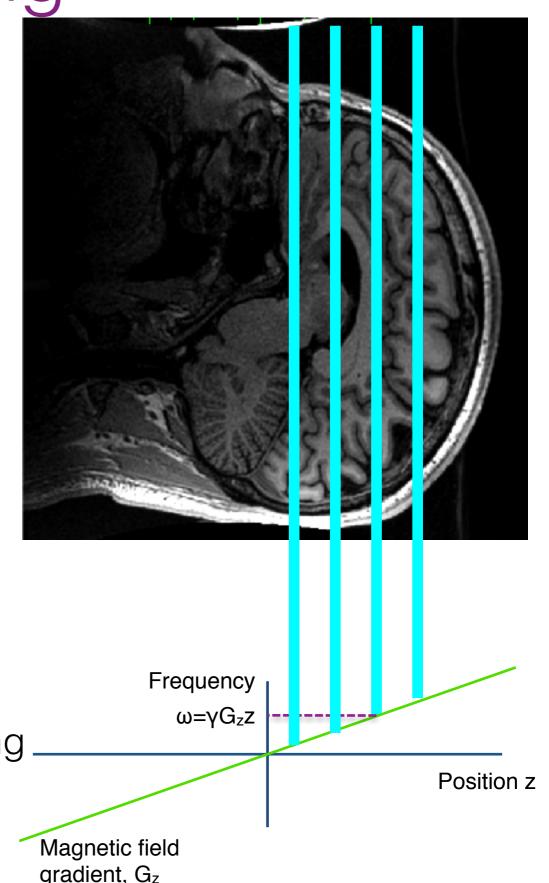
- Excite with frequency ω₀+δω to move slice from isocenter to position of interest.
- Excite with an RF pulse that is the composition of a band of frequencies to define a particular slice width.



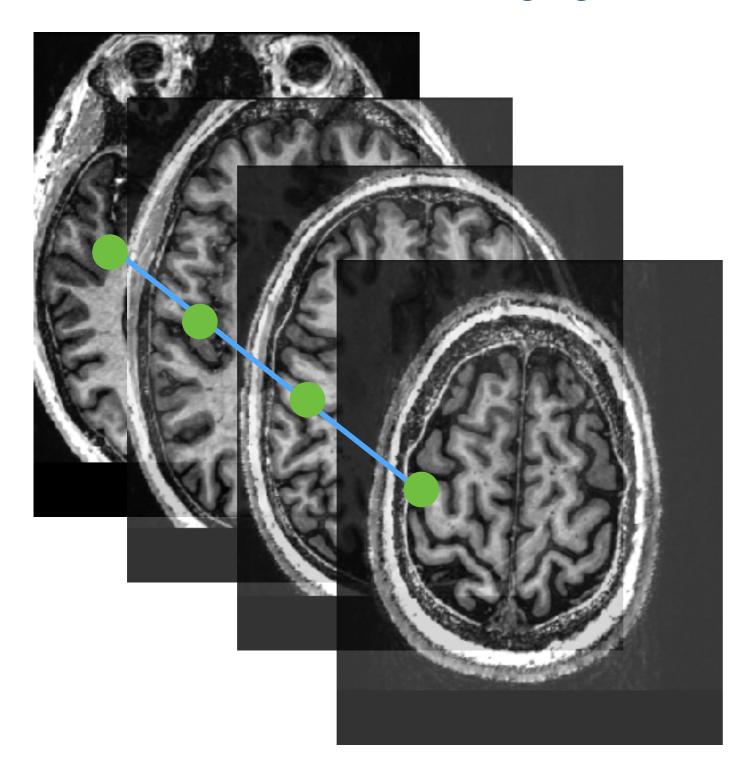
Simultaneous multi-slice imaging

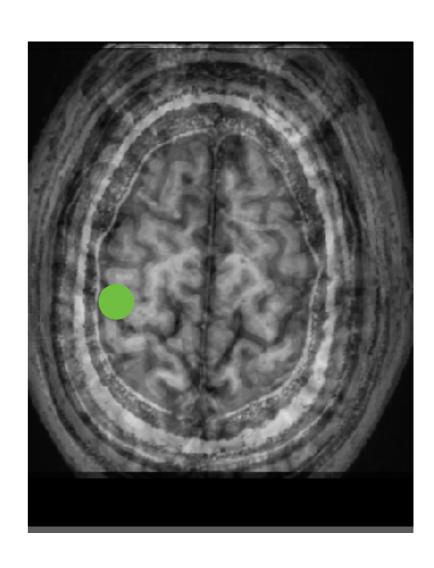
- Create RF pulse composed from the superposition of several (typically 2-12) bands of frequencies.
- Basically add a bunch of RF pulses (with specific frequency modulations) together
- Multiple slices excited with each RF pulse
- Works reasonably well when slices separated by >3 slice widths.

 Side effect: SMS RF pulses have significantly higher SAR than corresponding single slice excitations

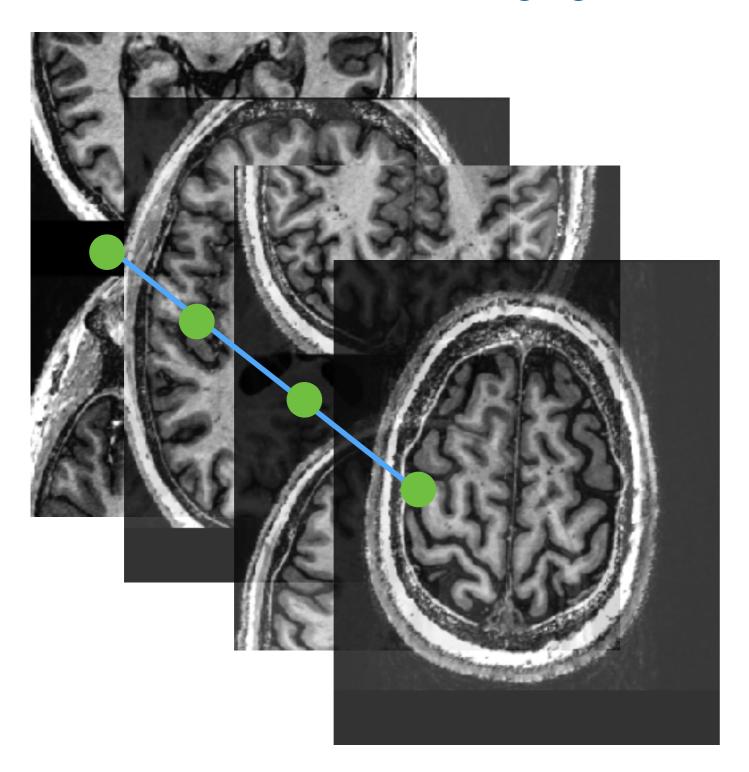


Simultaneous multi-slice imaging

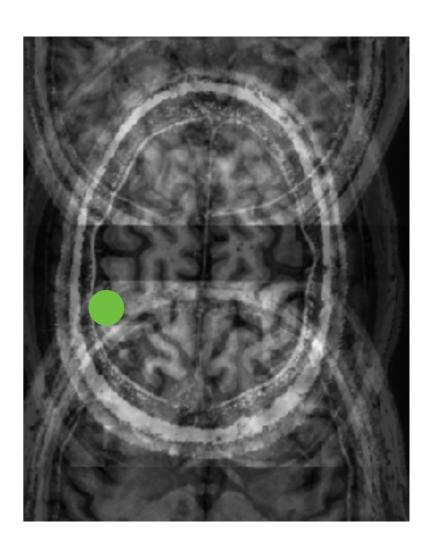




Simultaneous multi-slice imaging



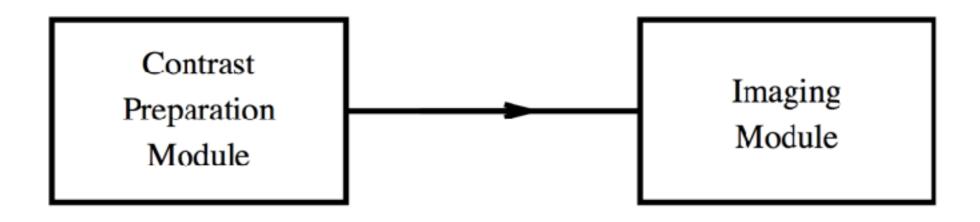
CAIPI



Improves g-factor (i.e. less noise)

Controlling image contrast

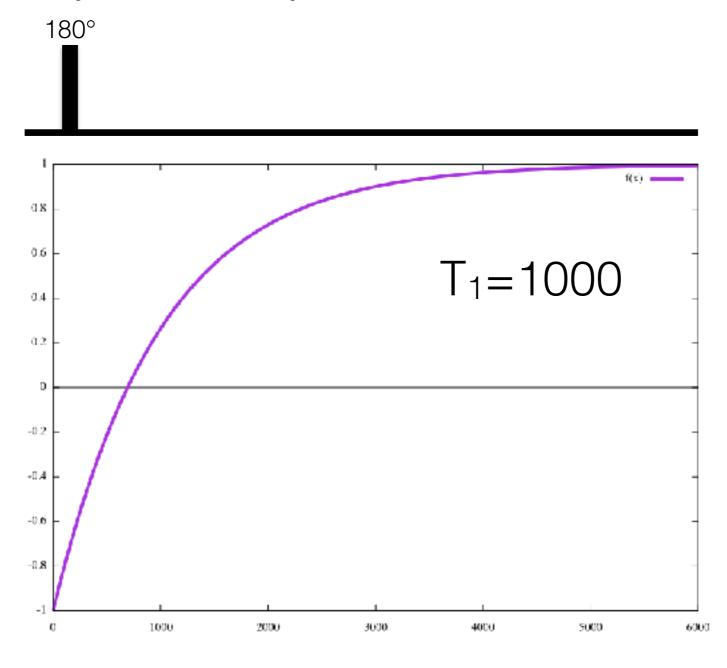
- Intrinsic contrast of the pulse sequence
 - Gradient-echo and spin-echo sequences
 - Effects of TE and TR
- Magnetization Preparation methods (examples)
 - Fat saturation
 - Flow preparation
 - Diffusion preparation



Inversion recovery

$$M_z(t) = M_0 + (M_z(0) - M_0)e^{-t/T1}$$

- Invert magnetization with 180° inversion pulse
- Magnetization slowly recovers by T₁



Inversion recovery

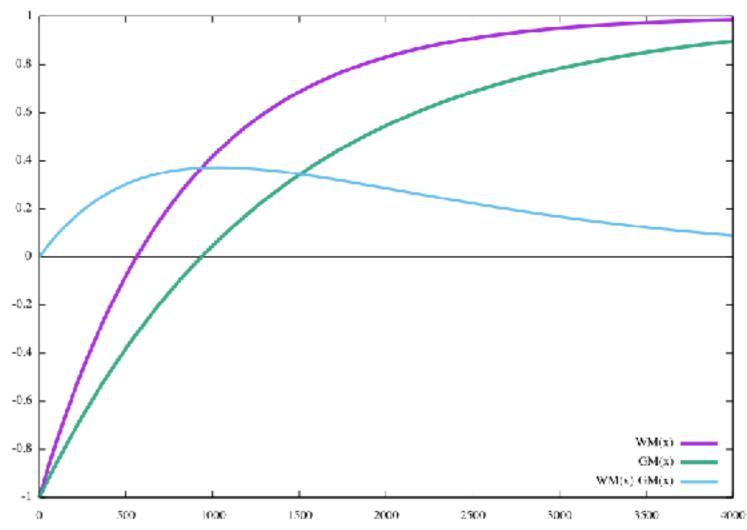
Contrast
Preparation
Module

Imaging
Module

 Prepare magnetization with 180° inversion pulse

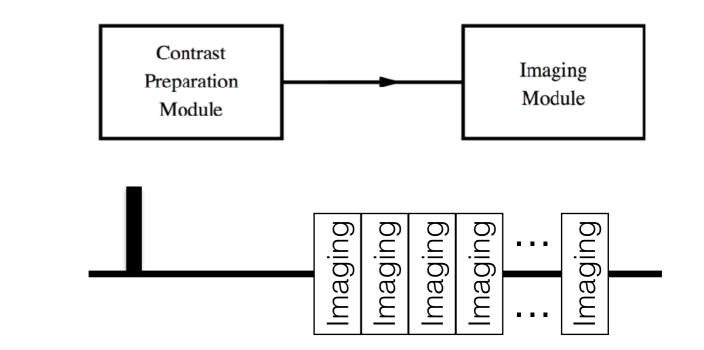
Imaging sequence

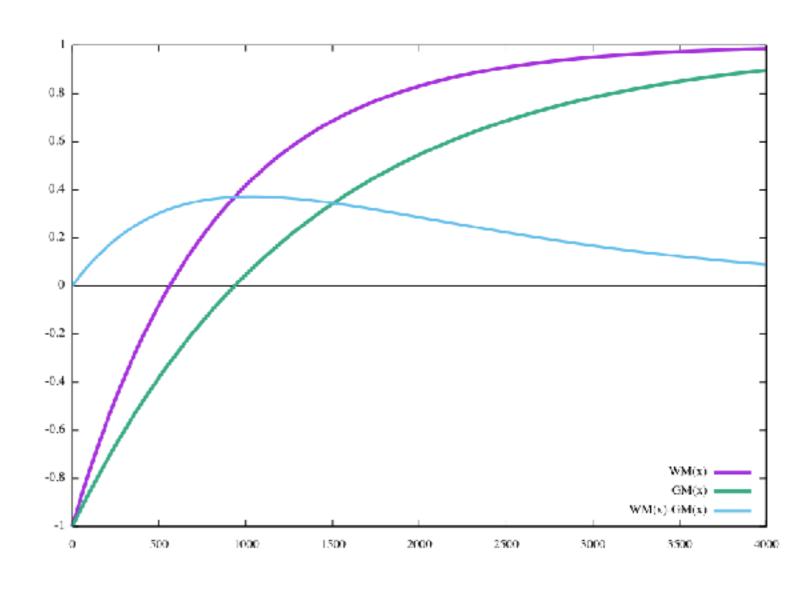
- Wait ...
 TI=inversion time.
- Perform imaging sequence.
- Obtain images with IR -0.2 contrast



MPRAGE

- Prepare
 magnetization with
 180° inversion pulse
- Wait TI for constrast to evolve
- Perform multiple imaging sequence acquisitions (typically do all kz, slice encodes)
- Repeat for all ky (phase encodes).





MP-RAGE

Magnetization Prepared Rapid Acquisition with Gradient Echoes

- 3D anatomical scan with white/grey matter contrast
- Typically:
 - 0.8-1.25mm isotropic resolution
 - 6 -12 minutes scan time

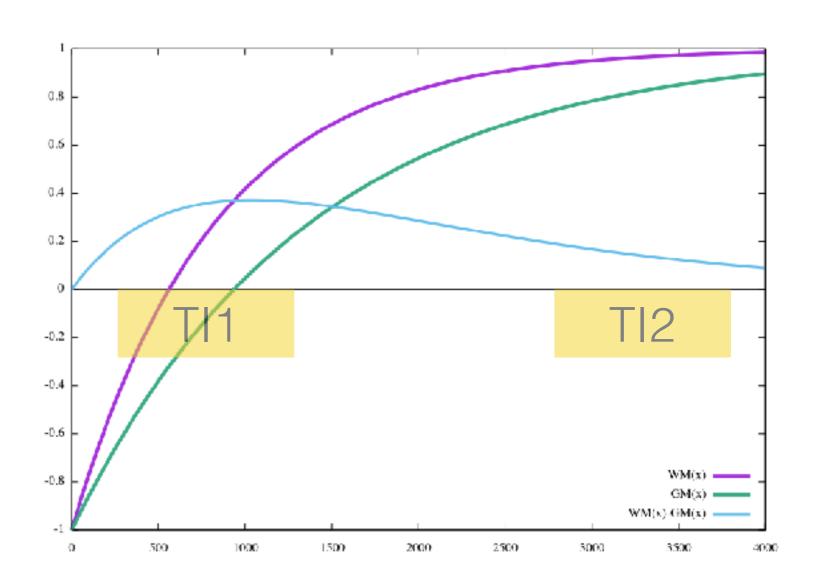
Multi-echo MPRAGE

- acquires images at multiple TEs during each imaging module
- Different T2* weightings

· MP2RAGE

- acquires images at two TIs (short, long) after each inversion pulse
- combined images can be used to compensate for variations in image intensity (e.g. due to coil profiles)
- Can generate estimated spatial maps of T₁ and T₂.

MP2-RAGE



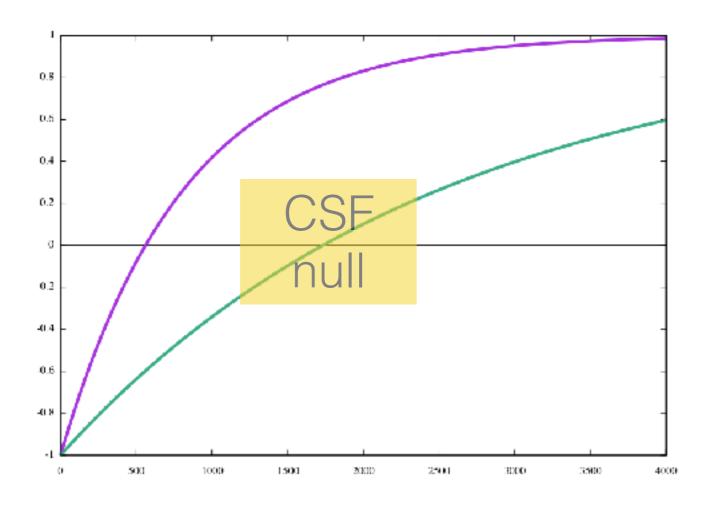
· MP2RAGE

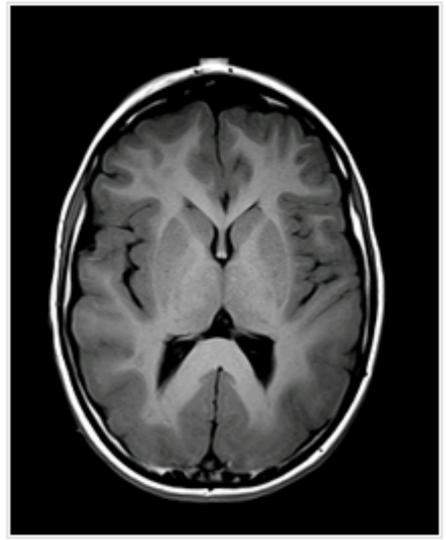
- acquires images at two TIs (short, long) after each inversion pulse
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- Can generate estimated spatial maps of T₁ and T₂.

FLAIR

Fluid attenuated inversion recovery

Null (long T1) signals due to fluid (e.g. CSF)





T1-FLAIR brain image at 3T with TR=2100, TE=9, TI=880.

- Often uses FSE/TSE for the imaging sequence
 - short TR for T1w-FLAIR
 - long TR for T2w-FLAIR

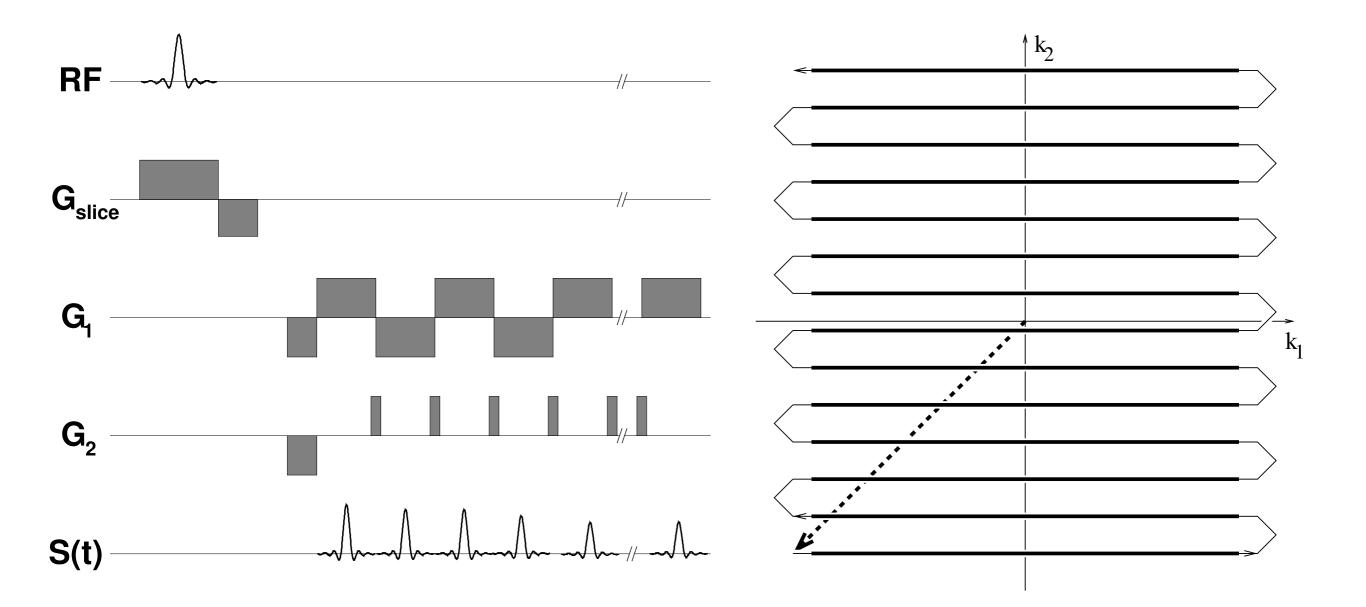
EPI

$\mathbf{k}(t) = \frac{\gamma}{2\pi} \int_0^t \mathbf{G}(t')dt'$

Echo planar Imaging

$$S(\mathbf{k}) = \int_{V} \rho(\mathbf{r}) \exp(i2\pi \mathbf{k} \cdot \mathbf{r}) d^{3}\mathbf{r}$$

- Acquire the whole 2D k-space after excitation
- Strong T2* weighting -- BOLD contrast



Safety

SAR and Gradient stimulation

- Specific absorption rate (SAR) is a measure of the rate at which energy is absorbed by the subject due to the RF (B1) field
- Peripheral nerve stimulation is caused rapidly changing magnetic fields (typically gradient) inducing electric fields in tissue causing stimulation of peripheral nerves.

Other stuff

Not covered in this talk

- Artifacts
- Motion monitoring/suppression
- Diffusion imaging
- Anything involving deeper NMR phenomena
- System engineering

Thanks for your attention

